

Simulation AI:

State of the art, best practices, trends

Two Sentiments



The Revolution

Omnipresence

Leaps in model ability

New models every month

The Mirage

Not much seems to work

Unclear what AI is supposed to do

Negative ROI

The Revolution



AI is **All Around Us**:



AI Generated Image
Workload: 2 seconds typing

- Text / Image / Video Generation
- Programming Tools
- Conference Presentations

The Revolution

AI in Simulation:

YASAI

The Revolution

AI in Simulation:

- Surrogate models for faster simulation results
- Near-real-time design evaluation
- Reduced-order models
- Neural operators for field prediction
- Geometry-to-field prediction
- Meshless flow/thermal prediction
- Fast pressure, temperature, stress, or velocity estimates
- Design-space exploration
- Optimization acceleration
- Inverse design
- Parameter studies
- Sensitivity analysis
- Uncertainty quantification
- Out-of-distribution detection
- Simulation result interpolation
- Simulation result extrapolation
- Digital twins
- Real-time monitoring models
- Predictive maintenance models
- Calibration of simulation models
- Model updating from test data
- Test/simulation correlation
- Material model identification
- Turbulence closure modeling
- Subgrid-scale modeling
- Boundary-condition estimation
- Initial condition estimation

- Automatic mesh generation
- Geometry cleanup
- CAD-to-simulation preparation
- Automated boundary labeling
- Simulation setup assistants
- Parameter recommendation
- Failure detection in simulation runs
- Convergence prediction
- Early stopping of bad simulations
- Error estimation
- Result plausibility checks
- Anomaly detection in fields
- Feature extraction from simulation results
- Automated postprocessing
- Report generation
- Engineering decision support
- Requirements-to-simulation mapping
- Knowledge capture from past projects
- Search over simulation archives
- Similar-case retrieval
- Reuse of historical simulation data
- Multi-fidelity modeling
- Combining 1D, 3D, test, and field data
- Generative design
- Physics-informed machine learning
- Physics-constrained prediction
- Data-driven correction of low-fidelity models
- Hybrid simulation/ML workflows
- AI copilots for CAE tools
- Natural-language access to simulation data
- Automatic documentation of simulation workflows
- Risk screening before expensive simulations



AI Race



New papers present better models every month:

- Transolver++ (2 /2025)
- GFocal (8 / 2025)
- PGOT (12 /2025)
- MGN-T (1 /2026)
- Transolver 3 (2 /2026)

Model	Structured Mesh			Point Cloud
	Plasticity	Pipe	Airfoil	Elasticity
WMT (2021)	0.0076	0.0077	0.0075	0.0359
U-FNO (2022)	0.0039	0.0056	0.0269	0.0239
Geo-FNO (2023a)	0.0074	0.0067	0.0138	0.0229
U-NO (2023)	0.0034	0.0100	0.0078	0.0258
F-FNO (2023)	0.0047	0.0070	0.0078	0.0263
LSM (2023)	0.0025	0.0050	0.0059	0.0218
Galerkin (2021)	0.0120	0.0098	0.0118	0.0240
HT-Net (2024)	0.0333	0.0059	0.0065	/
OFormer (2023c)	0.0017	0.0168	0.0183	0.0183
GNOT (2023)	0.0336	0.0047	0.0076	0.0086
FactFormer (2023d)	0.0312	0.0060	0.0071	/
ONO (2024)	0.0048	0.0052	0.0061	0.0118
IPOT (2024)	0.0033	/	0.0088	0.0156
Transolver (2024)	<u>0.0013</u>	<u>0.0043</u>	0.0053	<u>0.0079</u>
SAOT (2025)	0.0014	0.0062	<u>0.0051</u>	0.0090
PGOT (Ours)	0.0012	0.0039	0.0046	0.0069
Improvement	7.7%	9.3%	9.8%	12.7%

Table 4. Relative L2 errors (in %) of surface pressure p_s and skin friction coefficient C_f on the NASA-CRM dataset, and surface pressure p_s , volume velocity u , wall shear stress τ and volume pressure p_v on the AhmedML and DrivAerML datasets.

MODELS	NASA-CRM		AHMEDML				DRIVAERML			
	p_s	C_f	p_s	u	τ	p_v	p_s	u	τ	p_v
GRAPH U-NET*	15.85	15.61	6.46	4.15	7.29	5.18	16.13	17.98	27.84	20.51
GINO*	12.39	11.51	7.90	6.23	8.18	8.80	13.03	40.58	21.71	44.90
GAOT*	30.38	59.79	8.02	7.43	9.92	10.47	34.00	57.18	61.00	56.90
UPT	12.78	23.78	4.25	2.73	5.80	3.10	7.44	8.74	12.93	10.05
AB-UPT	9.77	<u>6.43</u>	3.97	1.94	5.60	2.07	<u>3.82</u>	5.93	7.29	<u>6.08</u>
TRANSOLVER*	9.61	<u>7.04</u>	<u>3.20</u>	1.81	<u>4.85</u>	2.41	4.81	6.78	8.95	7.74
TRANSOLVER++*	<u>9.51</u>	6.95	3.47	<u>1.78</u>	5.06	2.35	4.12	<u>4.70</u>	<u>6.42</u>	6.70
TRANSOLVER-3	8.71	5.85	2.96	1.60	4.81	<u>2.16</u>	3.71	4.14	5.85	5.72

The Mirage



Why do we see so little true impact?

The Mirage



Weak baselines and reporting biases lead to overoptimism in machine learning for fluid-related partial differential equations

Nick McGreivy^{1,2*} and Ammar Hakim²

^{1*}Department of Astrophysical Sciences, Princeton University, Princeton, New Jersey, USA.

²Princeton Plasma Physics Laboratory, 100 Stellarator Rd, Princeton, New Jersey, USA.

What's real?

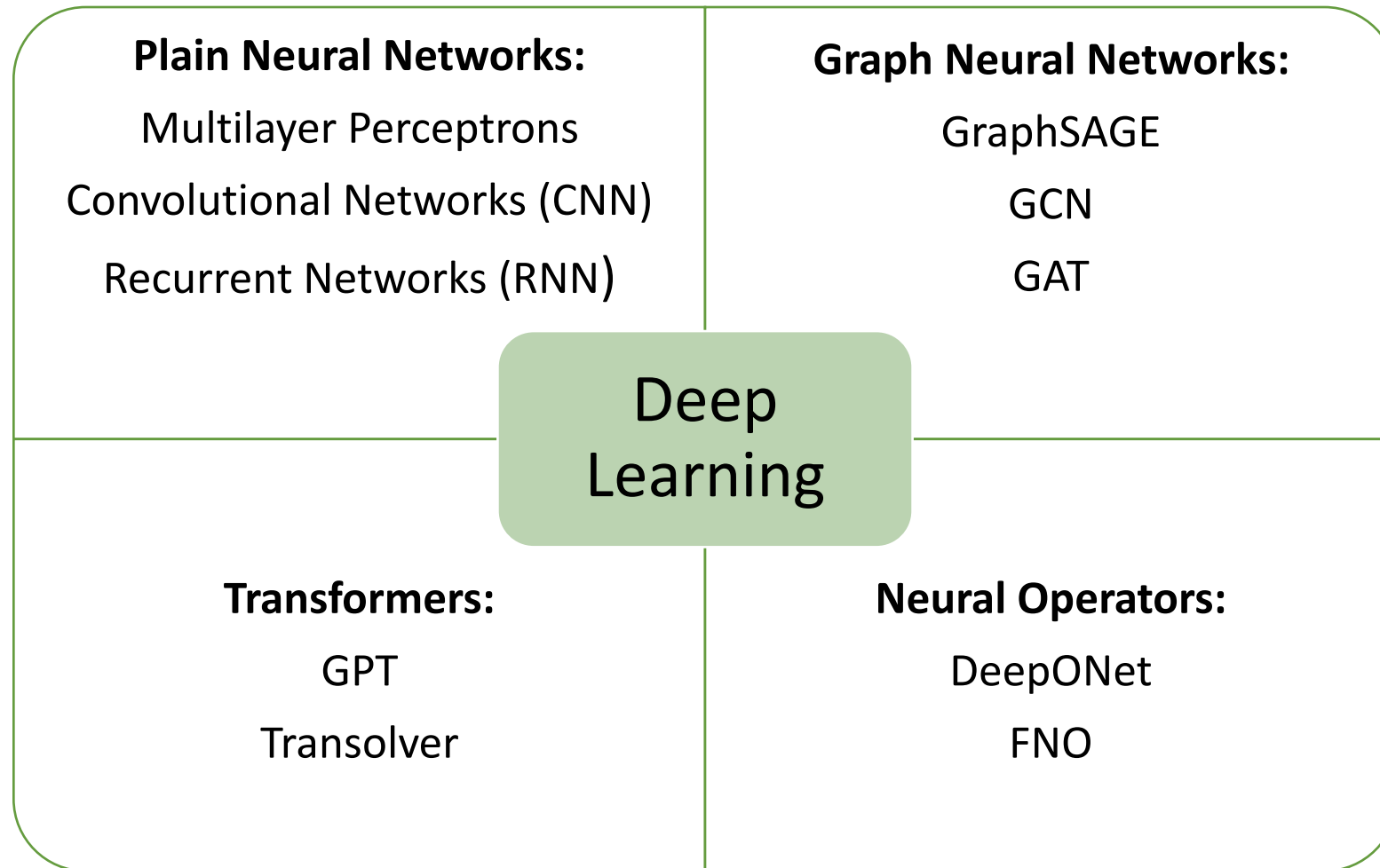
Hype

- 60 papers were overly optimistic or not reproducible
- An additional 6 papers published no improvement as result

Substance

- 16 papers did show **reproducible improvements** compared to standard numerical methods

Basic Model Types



Core Concepts



Convolution

- Spatial Correlations

Memory

- Sequential Correlations

Attention

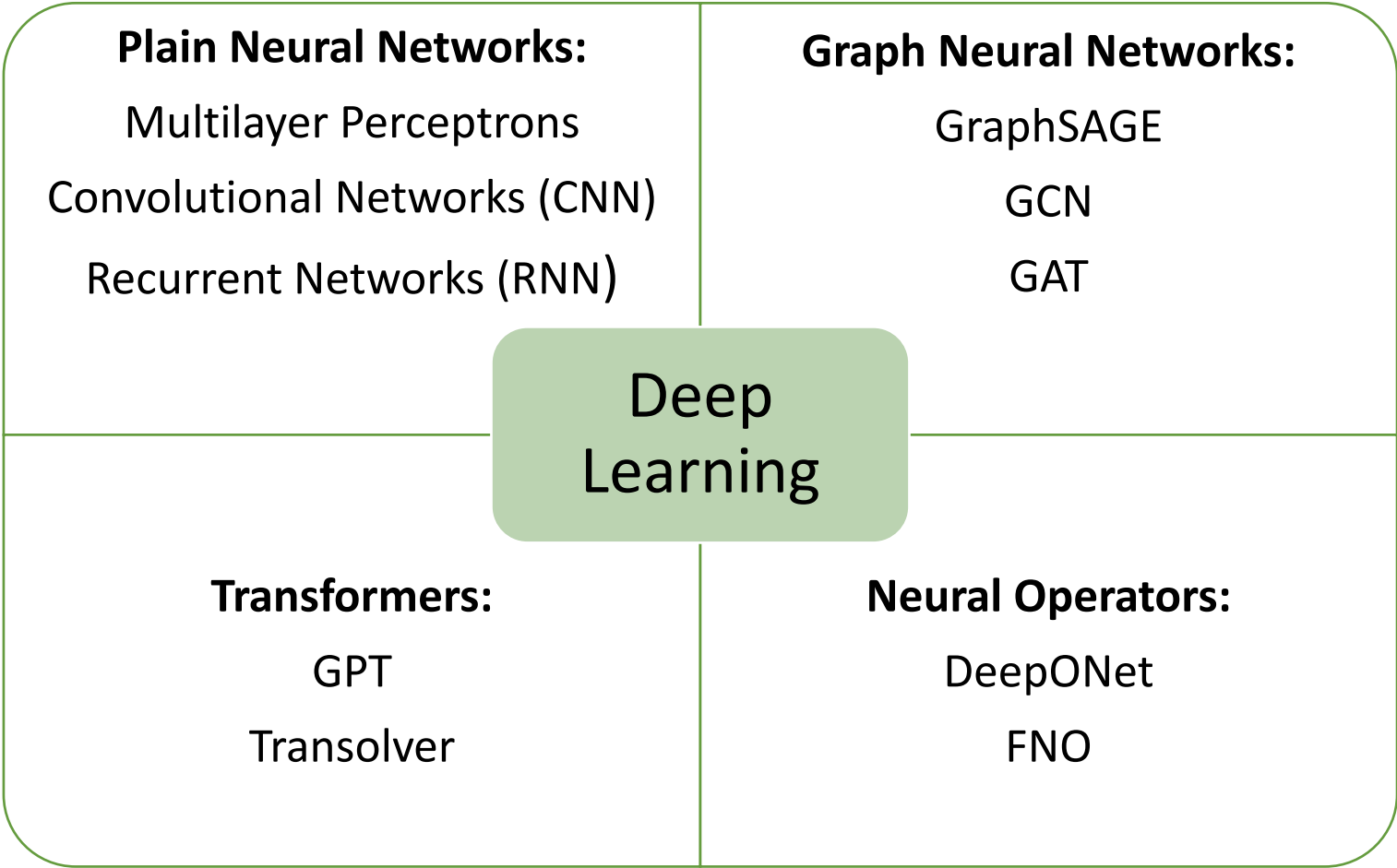
- Fully learned set-wise correlations

Physics Information

- Additional equations

Application

Research and production-ready models are usually derived from:



Convolution
• Spatial Correlations

Memory
• Sequential Correlations

Attention
• Fully learned set-wise correlations

Physics Information
• Additional equations

Application



Most model architectures are a blend of basic algorithms and broader concepts

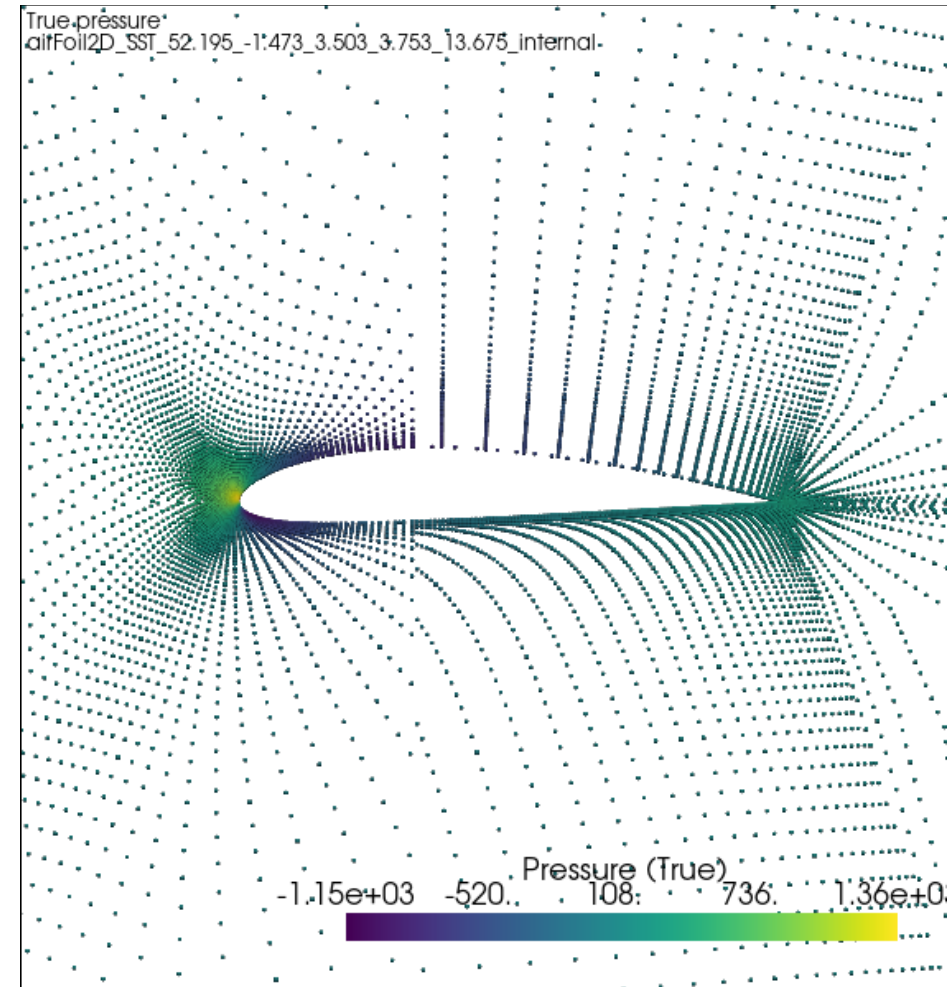
Example:

Transolver

Transolver



1. Groups datapoints into **slices with physical similarities**
2. An **attention function** weights the influence of a slice on all points
3. Predicts the field from **weighted slice features**



Application



There are dozens of new architectures published monthly

How do we know which ones are helpful?

Benchmarks



The variety of implementations makes benchmarking difficult

Table 2. Comparison on large geometries benchmarks. Relative L2 of the surrounding area (*Volume*) and surface (*Surf*) physics as well as drag and lift coefficient (C_D , C_L) is recorded, along with their coefficient of determination R_D^2 and R_L^2 . The closer R^2 is to 1, the better.

MODEL	DRIVAERNET++ FULL		DRIVAERNET++ SURF			AIRCRAFT		
	VOLUME ↓	SURF ↓	C_D ↓	R_L^2 ↑	SURF ↓	C_L ↓	R_L^2 ↑	SURF ↓
GRAPHSAGE (2017)	0.328	0.284	0.282	0.859	0.294	0.040	0.988	0.109
POINTNET (2017)	0.285	0.478	0.301	0.831	0.237	0.095	0.982	0.169
GRAPH U-NET* (2019)	0.241	0.260	0.272	0.876	0.193	0.063	0.953	0.161
MESHGRAPHNET* (2021)	0.529	0.422	0.260	0.870	0.209	0.038	0.993	0.113
GNO* (2020A)	0.510	0.664	0.252	0.882	0.196	0.031	0.991	0.129
GALERKIN* (2021)	0.234	0.274	0.267	0.792	0.235	0.069	0.879	0.118
GEO-FNO* (2022)	0.718	0.892	0.288	0.831	0.291	0.243	0.903	0.395
GINO (2023A)	0.586	0.638	0.323	0.725	0.220	0.047	0.983	0.133
GNOT* (2023)	0.174	0.171	0.158	0.901	0.167	0.033	0.991	0.093
LNO* (2024)	0.180	0.203	0.208	0.855	0.195	0.091	0.992	0.137
3D-GEOCA* (2024)	0.389	0.224	0.205	0.883	0.175	0.022	0.993	0.097
TRANSOLVER* (2024)	0.173	0.167	0.061	0.931	0.145	0.037	0.994	0.092
TRANSOLVER++ (OURS)	0.154	0.146	0.036	0.997	0.110	0.014	0.999	0.064
RELATIVE PROMOTION	11.0%	12.6%	41.0%	-	24.1%	36.3%	-	30.4%

* These models cannot directly handle million-scale meshes as the model input. Thus, to enable comparison, we split the input mesh of

Table 4. Relative L2 errors (in %) of surface pressure p_s and skin friction coefficient C_f on the NASA- p_s , volume velocity u , wall shear stress τ and volume pressure p_v on the AhmedML and DrivAerM

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Improvement	7.7%	9.3%	9.8%	12.7%

MODEL	POINT CLOUD
	ELASTICITY
WMT	0.0359
U-FNO	0.0239
GEO-FNO	0.0229
U-NO	0.0258
F-FNO	0.0263
LSM	0.0218
GALERKIN	0.0240
HT-NET	/
OFORMER	0.0183
GNOT	0.0086
FACTFORMER	/
ONO	0.0118
TRANSOLVER*	0.0060
GFOCAL (OURS)	0.0043
RELATIVE PROMOTION	28.3%

Model	RMSE-1	RMSE-all	#Param.	MPNN	Trans.	Hierarchy-free	Coarsen-free
MGN [18]	0.25	15.1	2.0M	✓	×	✓	✓
BSMS-GNN [32]	0.29	16.0	2.8M	✓	×	×	Prior
EvoMesh [35]	0.28	12.9	3.2M	✓	×	×	Learnt
HCMT [23]	-	7.3	2.5M	×	✓	×	Learnt
M4GN [37]	0.26	2.6	2.0M*	✓	✓	×	Prior
MGN-T (ours)	0.10	3.2	0.5M	✓	✓	✓	✓

Benchmarks



A few more independent benchmarks exist:

Table 3: Test errors (%) of branch-trunk neural operators. Bold indicates best performance.

Model	Heat sink	Bracket	Bracket-time	JEB
DeepONet	0.15%	5.90%	14.8%	-
Geom-DeepONet	0.18%	1.84%	15.1%	-
S-DeepONet	-	-	8.6%	-
S-NOT	-	-	5.6%	-
DCON	0.10%	1.75%	10.7%	-
GANO	0.16%	1.86%	12.9%	47.1%

Table 4: Test errors (%) of general-geometry models without parametric inputs.

Model	Heat sink	Bracket	JEB	DrivAerNet	DrivAer++
Best branch-trunk	0.10% (DCON)	1.75% (DCON)	47.1% (GANO)	23.1% (GANO)	21.8% (GANO)
GNO	5.69%	10.14%	61.1%	45.8%	33.8%
EA-GNO	6.12%	10.88%	58.6%	48.7%	35.8%
MechGraphNet	5.94%	11.27%	62.9%	49.6%	46.5%
GI-FNO	1.21%	3.94%	31.2%	25.6%	19.8%
FigConvUNet	0.89%	3.80%	29.8%	23.7%	18.3%
PointNet	6.14%	8.75%	40.1%	28.5%	18.8%
GNOT	5.55%	3.58%	37.6%	17.9%	18.3%
Transolver	5.23%	2.74%	36.6%	16.7%	17.3%

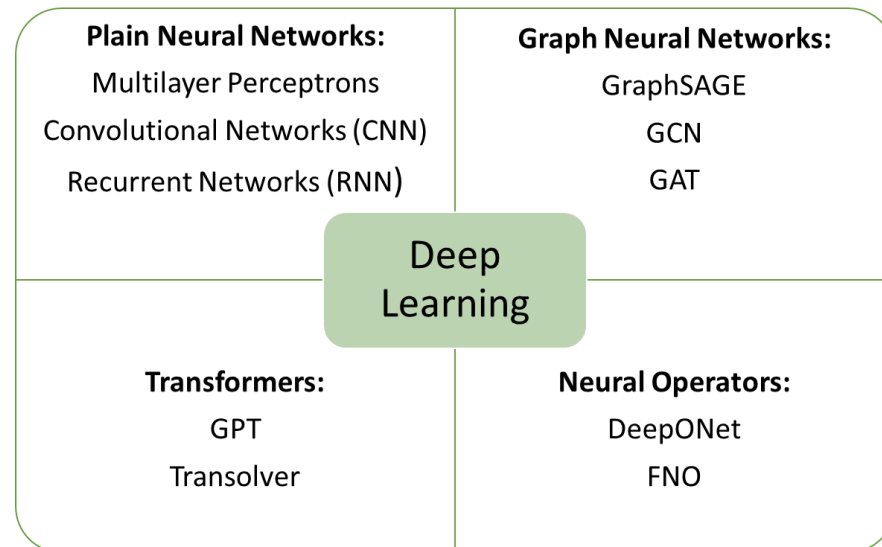
Benchmarks

NAFEMS Benchmark (results in october):

- AirfRANS Dataset (1000 NACA airfoils)
- Open-Source Models
- Vendor software?

What Works

16 models tested in the weak baselines paper were truly faster than numerical solvers



Successful architectures:

- Plain neural networks
- Convolutional networks
- Recurrent networks

What Works

Common applications

Design Space Exploration:

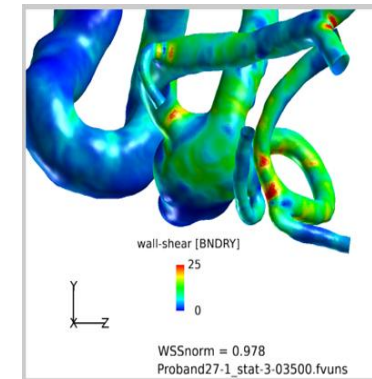
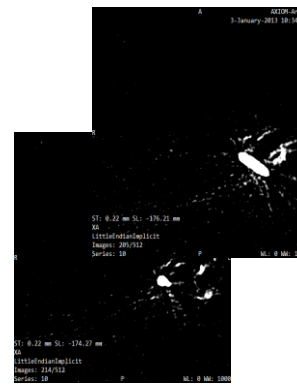
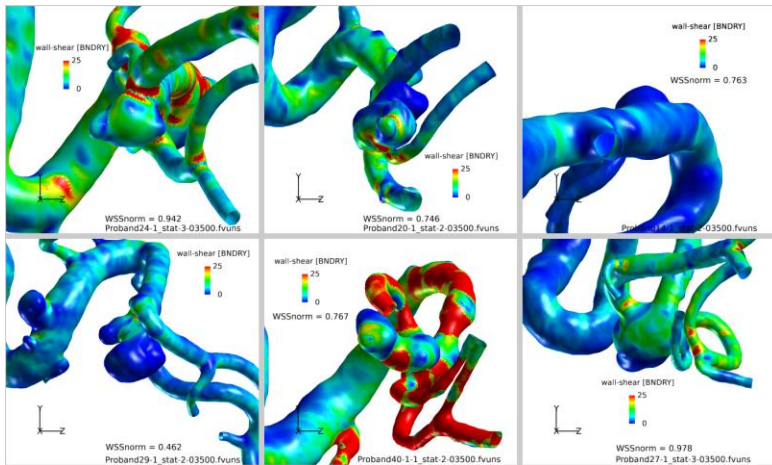
- Efficient DoE
- Optimize Designs
- Often: Tabular Regression

(Near) Real-Time Fields:

- Frontloaded Simulations
- Useful when time matters
- Essentially: Very efficient lookup and intelligent interpolation

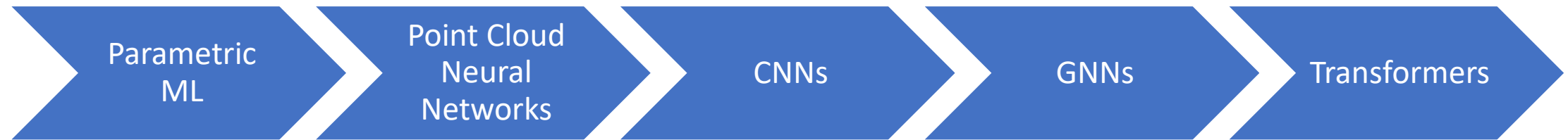
Aneurysm Prediction

YASAI



A larger dataset is used to train the AI

Efficiency



Low Complexity

Megabytes of Data
Datatables
Local CPU Training

Model Complexity ~
(Dataset Size / Inductive Bias)

High Complexity

Petabytes of Data
Lakes of Sim Data
Cloud GPU Training

Pitfalls



Avoiding pitfalls

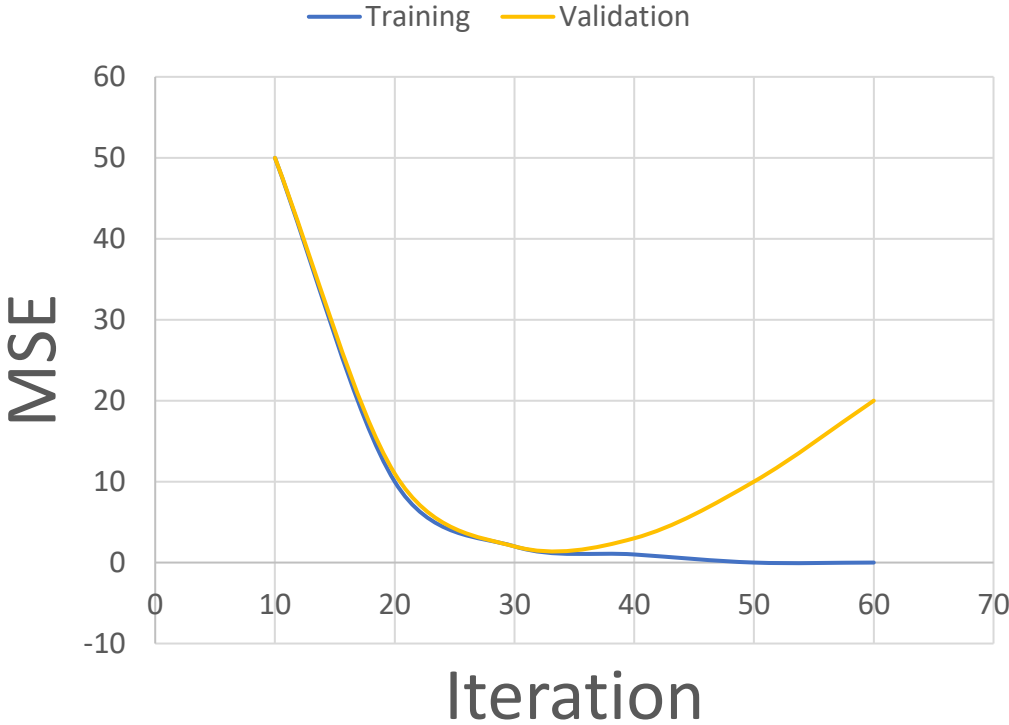
Overfitting

Leakage

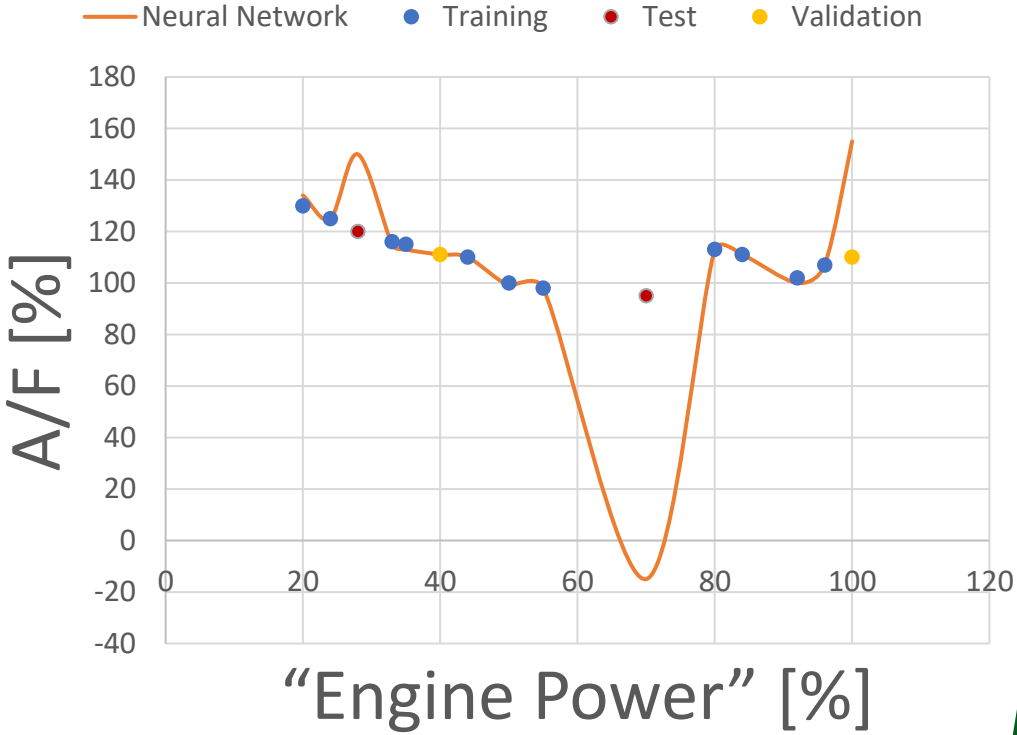
Artifacts

Overfitting

Training Loss



60 Training Iterations



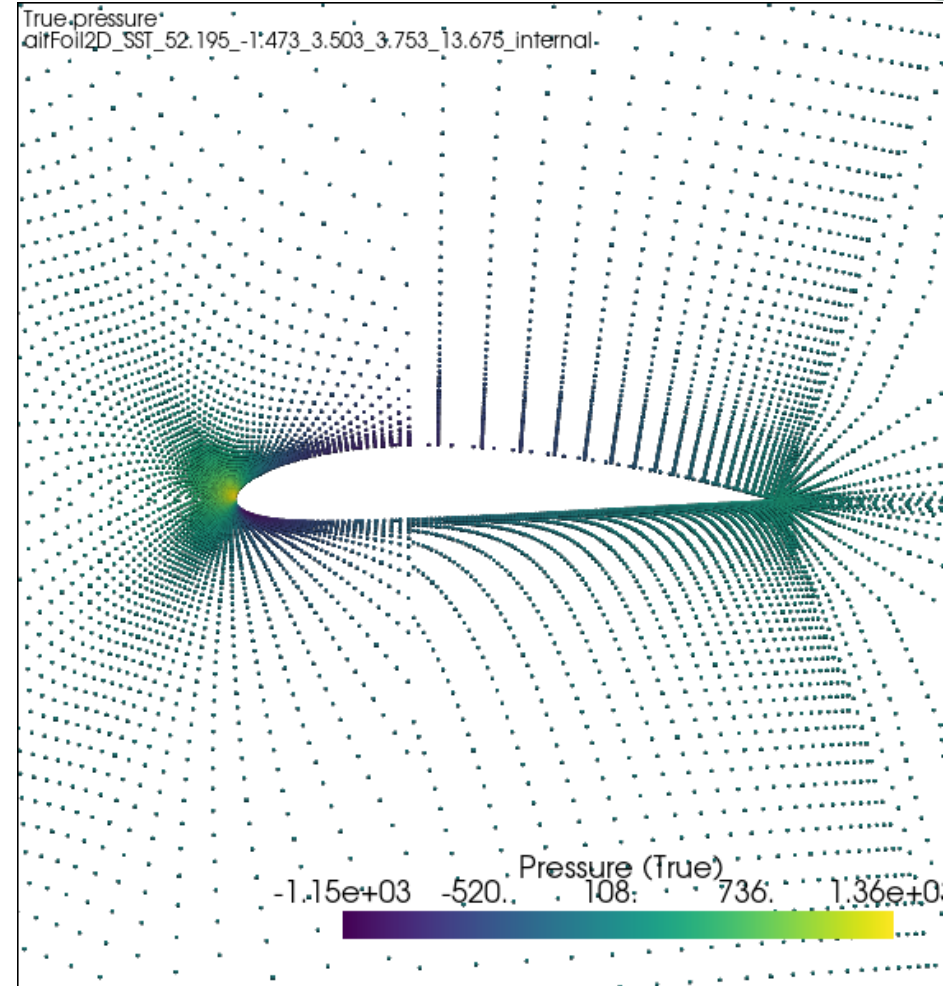
Leakage

**A model can look good on test data
and still be wrong**

Leakage

Example:

- Training pressure fields for airfoils
 - Training data contains all geometries
 - Test data uses different held out inlet velocities
- The model will memorize pressure fields



➔ **Predictions for new geometries will be off**

Leakage

Leakage:

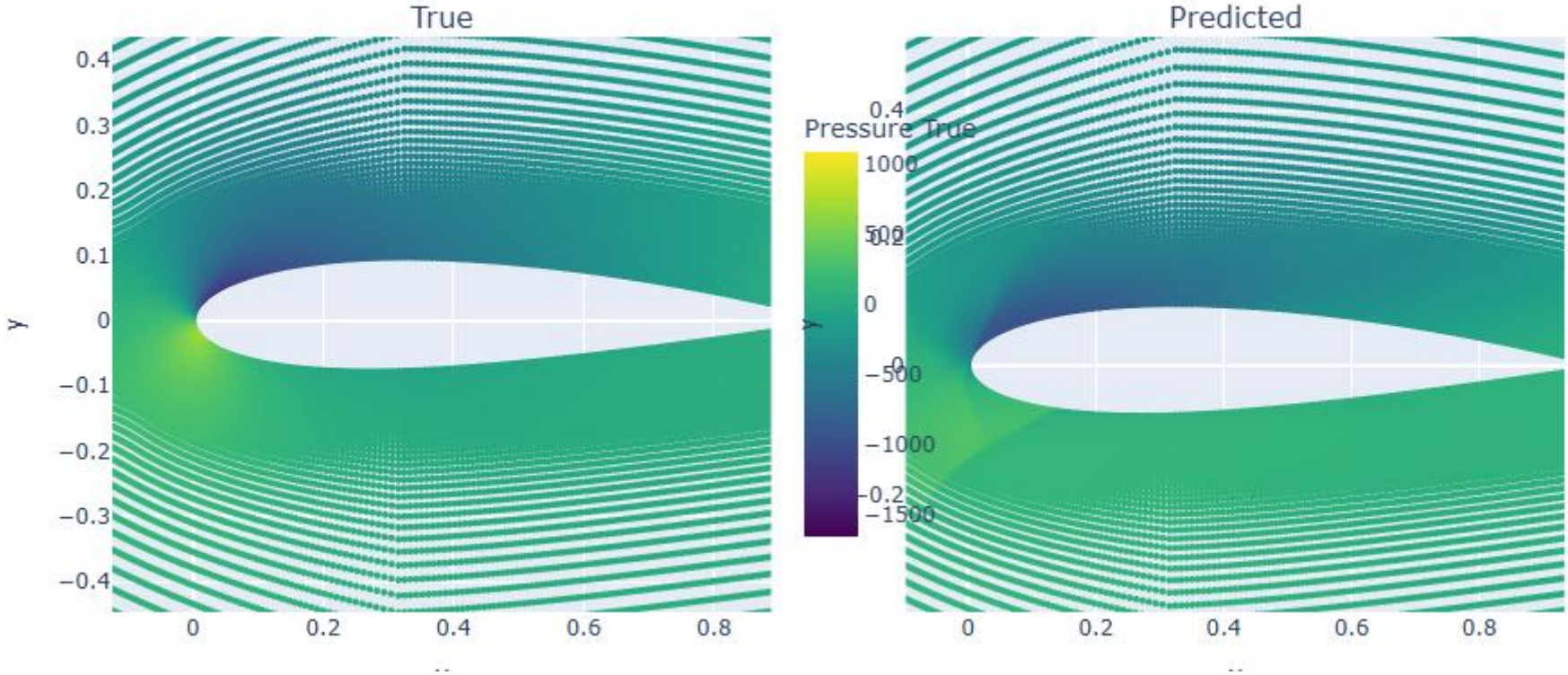
- Model has information at training time that is not available on unseen data
- Analogy: Memorizing without understanding

Effect:

- Models show very good results on test data
- But perform poorly on anything new

Artifacts

Artifacts are hardly quantifiable



PINNs

Physics informed neural networks (PINN):

- Don't have to stick to their physics terms
- Introduce additional numerical instability and computational overhead
- Don't outperform numerical solvers

Physics information can be helpful *and* harmful

More Practical Advice

Prerequisites to build a Sim-AI model:

- Simulation and application knowledge
 - Example Aneurysm AI:
 - Simulation Specialists
 - Radiologists
 - Neurosurgeons
- Cross-sectional ML expertise
- A clear project goal!

More Practical Advice



The most useful AI systems are tailored to a specific application.

There is no general-purpose pipeline.

More Practical Advice



How to tell if an AI product is useful:

Remove AI from the description.

More Practical Advice



AI is data-driven by definition:

- It makes use of simulations
- It can't replace simulation

The logo for YASAI features the word 'YASAI' in a stylized font. The 'Y' is a solid green block letter with a dark green shadow. The 'A' is a thin green outline. The 'S' is a thin green outline. The 'AI' are solid green block letters. The background is white with a green geometric shape on the right side.

YASAI

Max Kassera

kassera@yas-ai.com

+49 160 1722246

www.yas-ai.com