



# Forum **TERATEC** 24

**Unlock the future**

## **AI, Gen AI and the Metaverse: A New Era of Possibilities and Challenges.**

Valerio Rizzo, PhD | Lenovo EMEA Head of AI & Metaverse SME

**Lenovo**

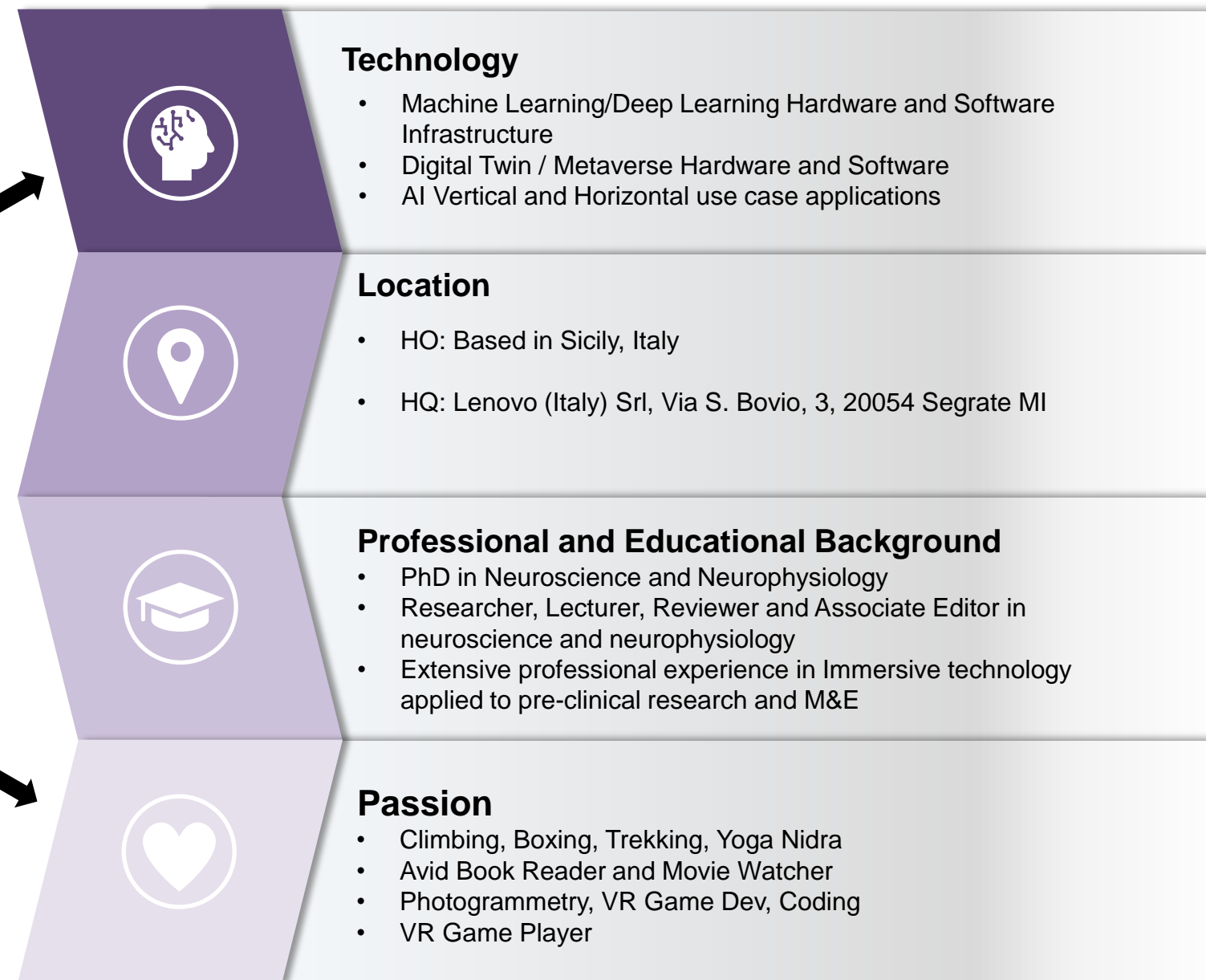
 **nVIDIA.**

# About Me



**Valerio Rizzo, PhD**

| EMEA HEAD of AI & Metaverse SME  
| Lenovo (Italy) Srl | ISG  
| email: [vrizzo@lenovo.com](mailto:vrizzo@lenovo.com)

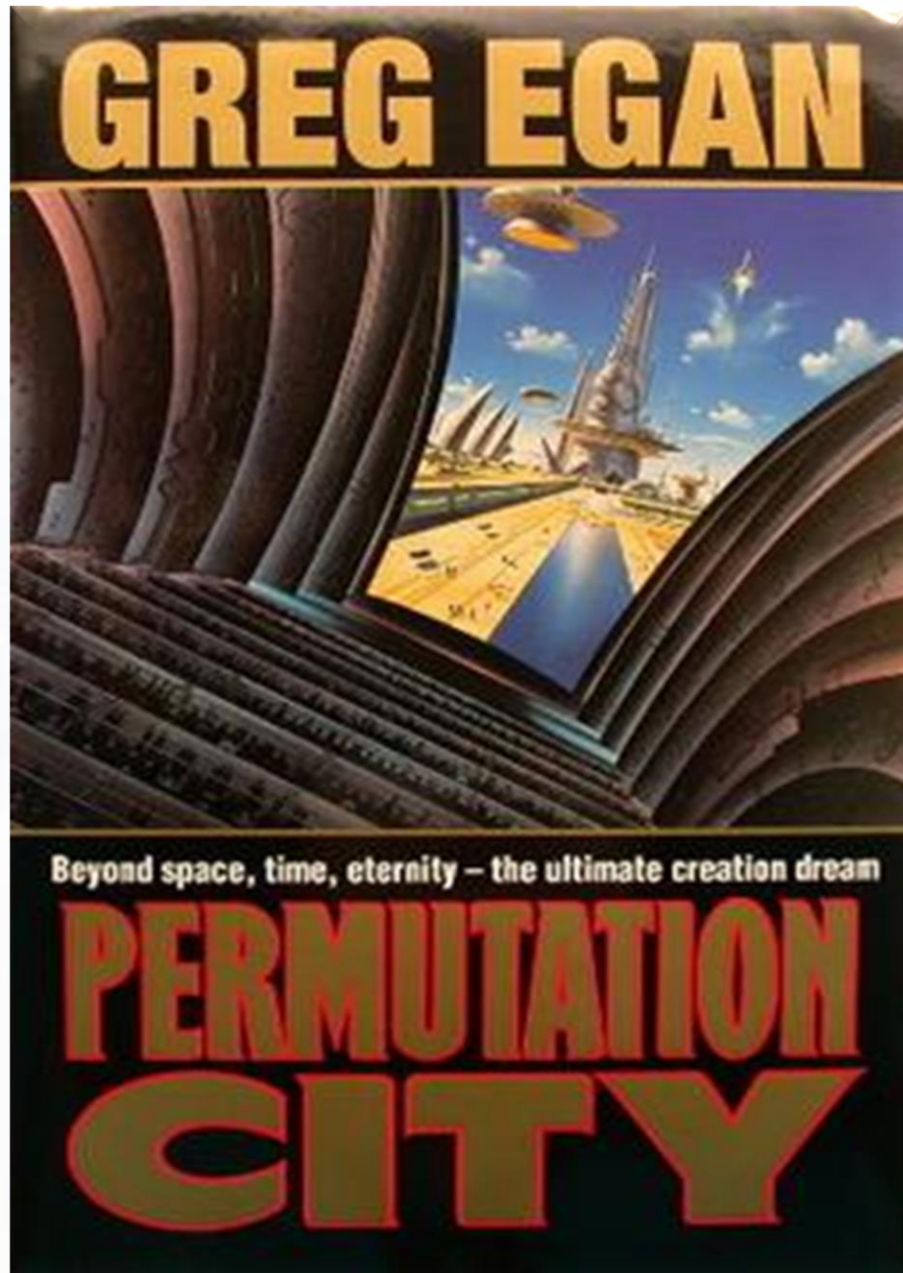


## Unlock the future

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# From Fiction to Science



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## ARE YOU LIVING IN A COMPUTER SIMULATION?

BY NICK BOSTROM

[Published in *Philosophical Quarterly* (2003) Vol. 53, No. 211, pp. 243-255. (First version: 2001)]

This paper argues that *at least one* of the following propositions is true: (1) the human species is very likely to go extinct before reaching a “posthuman” stage; (2) any posthuman civilization is extremely unlikely to run a significant number of simulations of their evolutionary history (or variations thereof); (3) we are almost certainly living in a computer simulation. It follows that the belief that there is a significant chance that we will one day become posthumans who run ancestor-simulations is false, unless we are currently living in a simulation. A number of other consequences of this result are also discussed.

### I. INTRODUCTION

Many works of science fiction as well as some forecasts by serious technologists and futurologists predict that enormous amounts of computing power will be available in the future. Let us suppose for a moment that these predictions are correct. One thing that later generations might do with their super-powerful computers is run detailed simulations of their forebears or of people like their forebears. Because their computers would be so powerful, they could run a great many such simulations. Suppose that these simulated people are conscious (as they would be if the simulations were sufficiently fine-grained and if a certain quite widely accepted position in the philosophy of mind is correct). Then it could be the case that the vast majority of minds like ours do not belong to the original race but rather to people simulated by the advanced descendants of an original race. It is then possible to argue that, if this were the case, we would be rational to think that we are likely among the simulated minds rather than among the original biological ones. Therefore, if we don't think that we are currently living in a computer simulation, we are not entitled to believe that we will have descendants who will run lots of such simulations of their forebears. That is the basic idea. The rest of this paper will spell it out more carefully.

Apart from the interest this thesis may hold for those who are engaged in futuristic speculation, there are also more purely theoretical rewards. The argument provides a stimulus for formulating some methodological and metaphysical questions, and it suggests naturalistic analogies to certain traditional religious conceptions, which some may find amusing or thought-provoking.

The structure of the paper is as follows. First, we formulate an assumption that we need to import from the philosophy of mind in order to get the argument started. Second,

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**T**erry Schneider, an Associate Technical Fellow in Boeing Research & Technology, works in “atoms to airplanes” modeling, or the complete process of modeling an airplane computationally from a molecular level up to the full-scale, complete airframe. One important goal of this work is to optimize the chemistry of polymers to increase the load-carrying capability of the carbon fiber in composites, which could significantly reduce the weight of next-generation composite structures. “This is exciting work because we’re able to rapidly assess hundreds of polymer candidates in a matter of weeks—a process that might take years in a lab,” Schneider said. “We’re also able to quickly determine their performance in large-scale laminated structures and screen for the best-performing candidates. This opens the door to huge cost savings in the future.” Work such as this demonstrates the benefits to Boeing generated by the company’s enterprisewide approach to making research investments in key areas such as structures, a term that describes the physical airframe components of airplanes and other aerospace products. Critical aviation design issues—including weight, reliability and safety—all depend on the quality of research and planning that drives structures engineering. Boeing has long been a leader in structures technology, and research conducted throughout the enterprise has steadily improved the design of structures and the materials used to make them. The challenge today is to increase the company’s competitive edge by investing in research that generates maximum benefit for Boeing’s range of products, both commercial and military. That’s why, in 2008, the company created its Enterprise Technology Strategy (ETS), which takes a coordinated, “One Company” approach to technology development. The strategy is built around eight technology areas, or domains, that support Boeing’s many business programs and can create a sustainable technical competitive advantage that helps the company grow.

DECEMBER 2009—JANUARY 2010 / BOEING FRONTIERS

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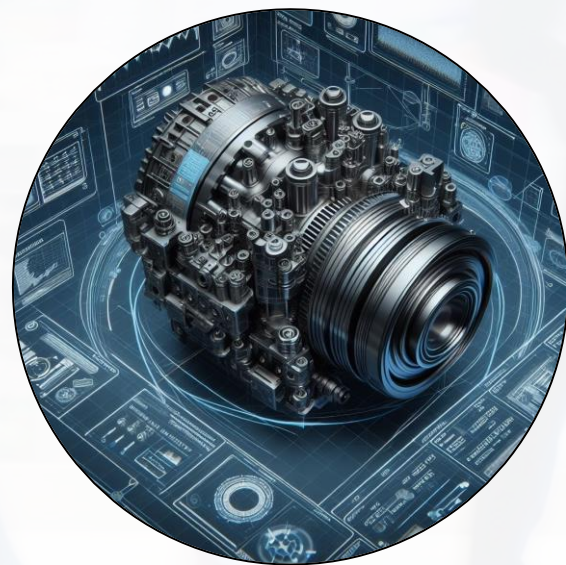
# From Digital Twin to Industrial Metaverse

Industrial Metaverse

Whole-System DT

Immersive DT

Digital Twin



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*Connected whole-system digital twin with functionalities to interact with the real system in its environment, allowing decision makers to better understand the past and forecast the future.”*

*Arthur D. Little*

## SIEMENS

A virtual world in which we can **interact in real time with photorealistic, physics-based digital twins** of our real world. We believe **digital twins are the building blocks for the Metaverse.**



Industrial Metaverse enables industrial companies of all sizes to create **closed-loop digital twins with real-time performance data, ideal for running simulations and AI-accelerated processes for advanced applications such as autonomous factories that rely on intelligent sensors and connected devices.**

## IndustrialMetaverse.org

A real-time, persistent simulation space that is the **sum of all virtual worlds, digital twins, and augmented reality that connects digital economic assets and infrastructure on a global scale in the industrial and commercial setting.**



Industrial Metaverse enables **humans and AI to work together to design, build, operate, and optimize physical systems** using digital technologies.



A **systematic discipline that combines hardware [...] data conversions** through analytics/machine learning, **time histories** through cyber-infrastructure, **cognition** through human-machine interface, and **configuration** through the Metaverse.



The Industrial Metaverse enables the creation of **digital twins of places, processes, real-world objects, and the humans who interact with them.**

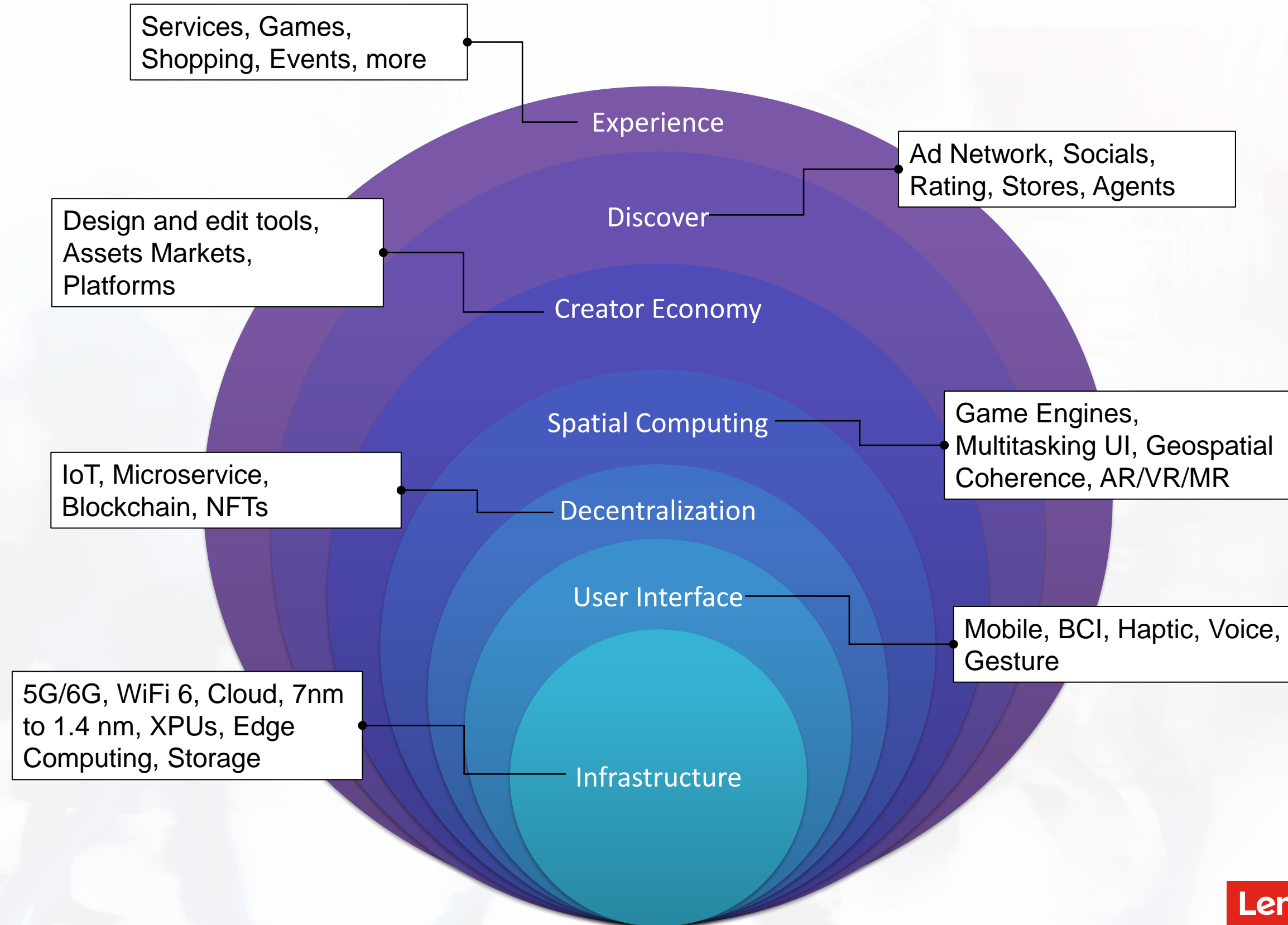
Source: Arthur D. Little

“

*A massively scaled and interoperable network of real-time rendered 3d virtual worlds that can be experienced synchronously and persistently by an effectively unlimited number of users with an individual sense of presence and with continuity of data, such as identity, history, entitlements, objects , communications and payments ”*

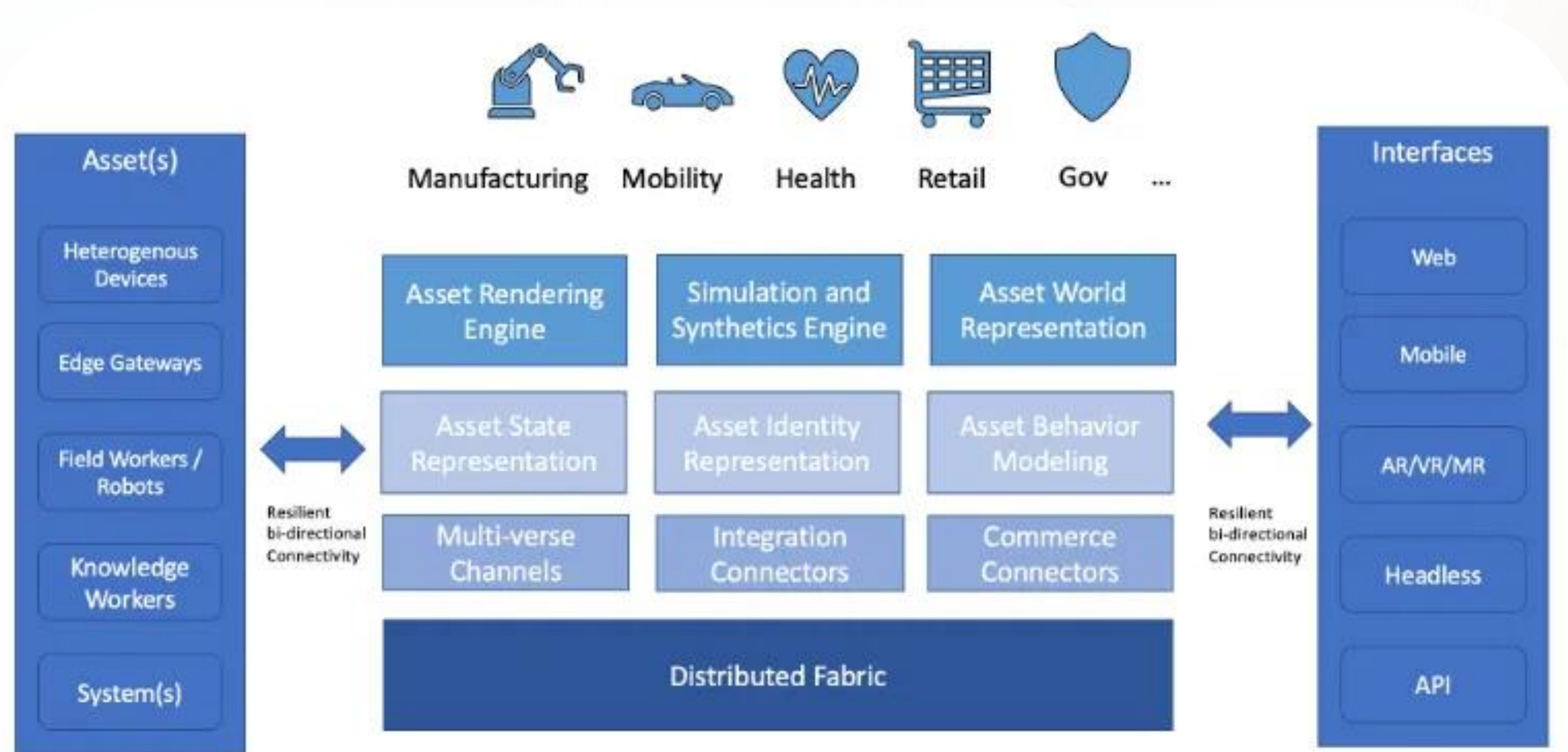
*Matthew Ball, The Metaverse*

# Anatomy of the Metaverse





# Metaverse System Model





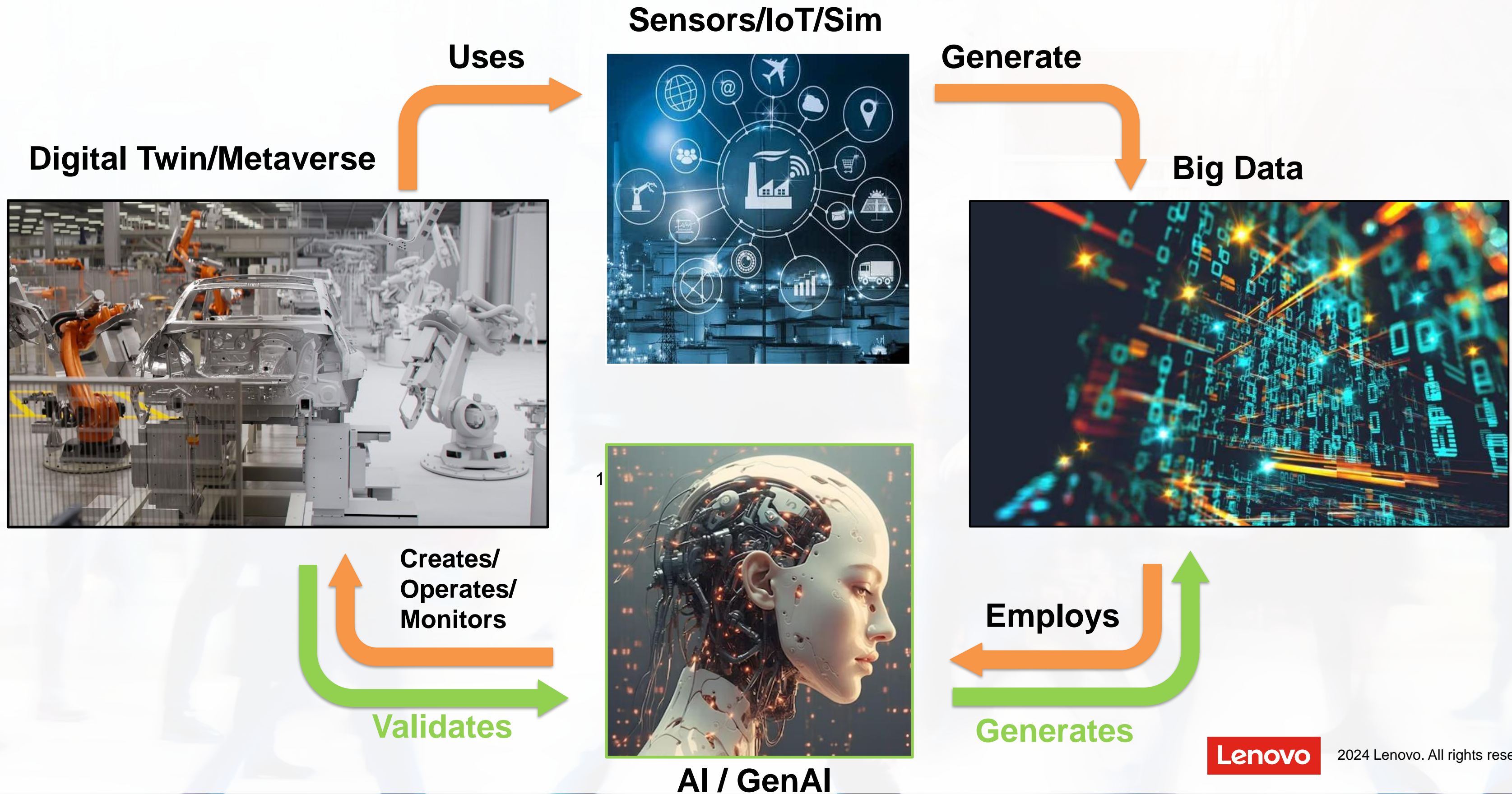
*The natural habitat of AI  
is in the virtual world.”*

*Dr. Michael Grieves*

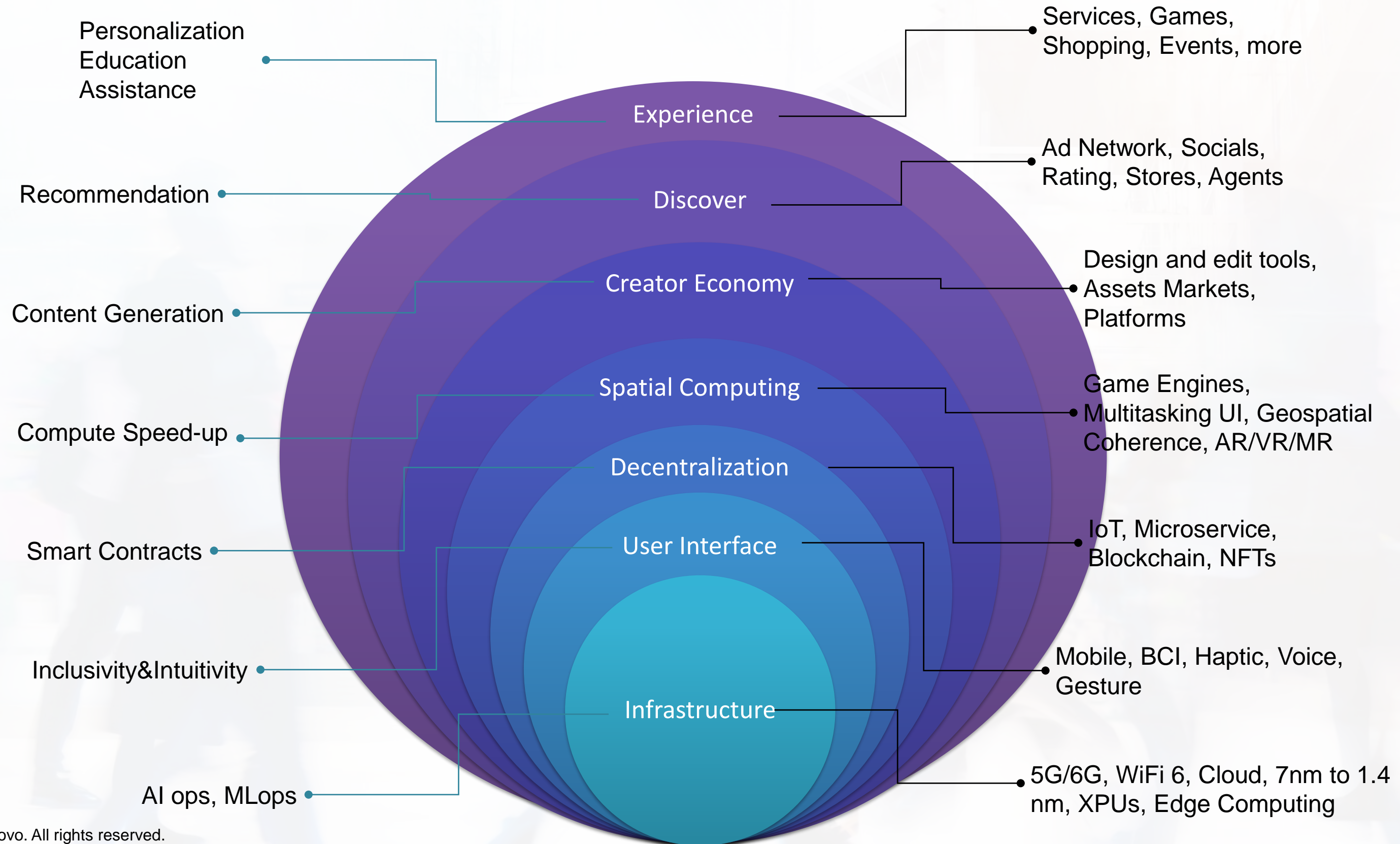
*- Intelligent digital twins and the development and management of complex systems -*



# The Intertwined Nature of Metaverse and AI



# AI value for the Metaverse



# How Today's AI is Shaping Tomorrow's Possibilities

3D Modeling & Visualization



Decentralized Computing



Network Optimization



Confidential AI Solutions



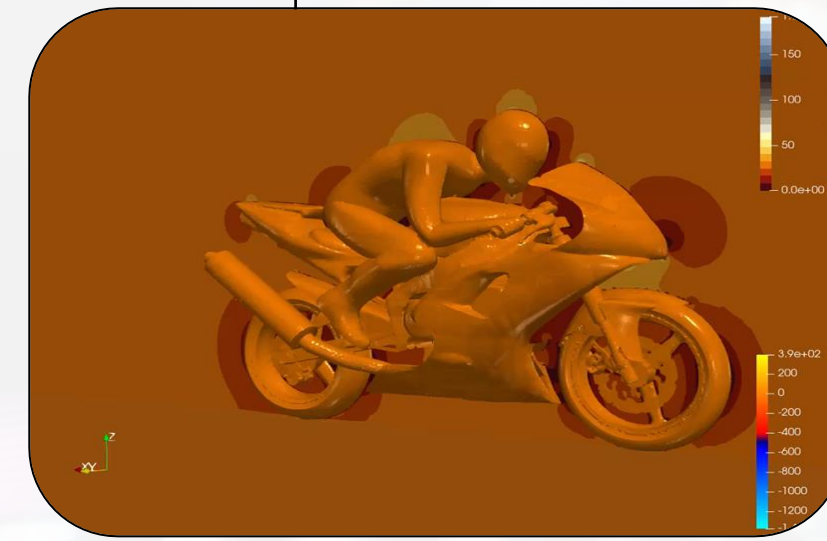
## INDUSTRIAL METAVERSE



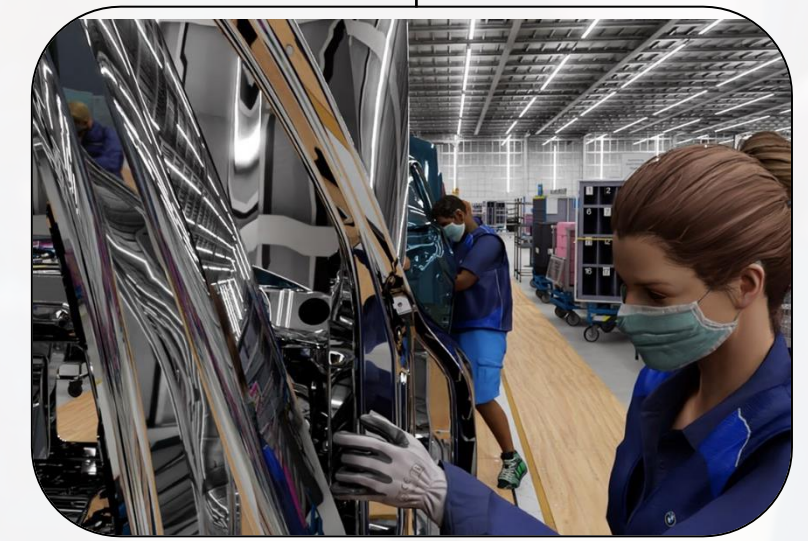
Spatial Computing



Human-Machine Interactivity



Physically Accurate Simulations



Realistic Interactive Virtual Entities

# How Today's AI is Shaping Tomorrow's Possibilities

3D Modeling & Visualization



Decentralized Computing



Network Optimization



Confidential AI Solutions



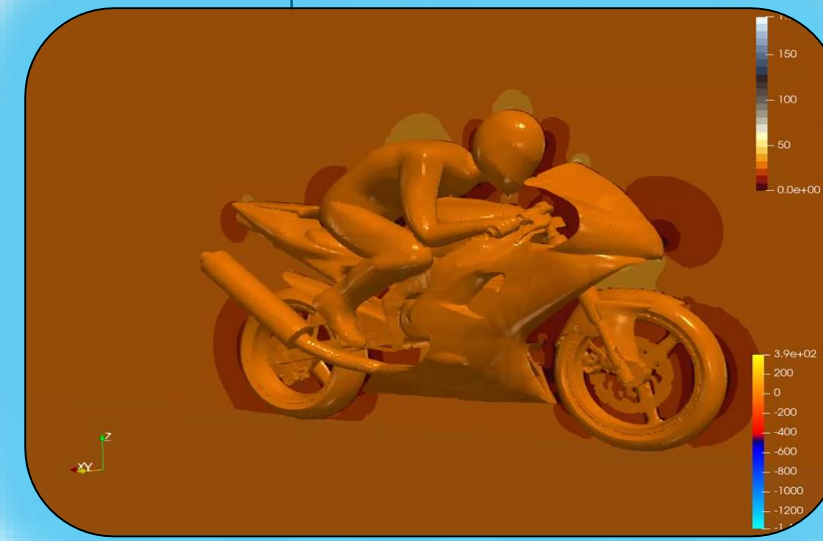
## INDUSTRIAL METAVERSE



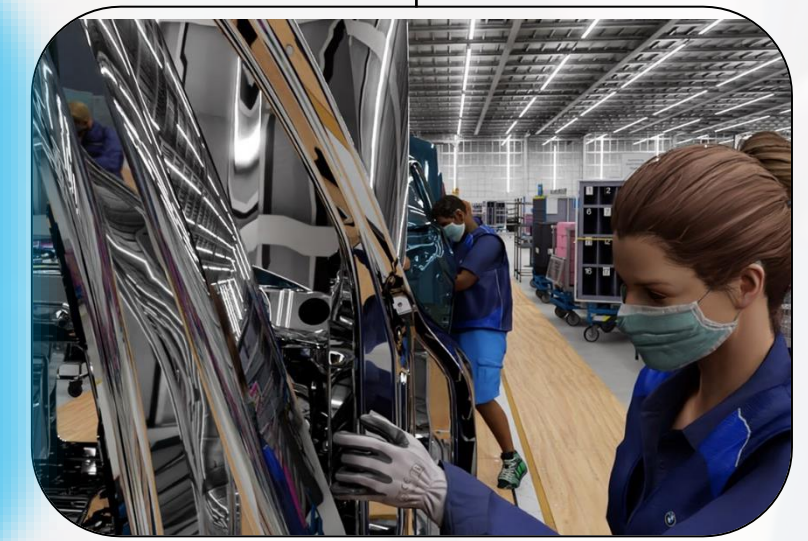
Spatial Computing



Human-Machine Interactivity



Physically Accurate Simulations



Realistic Interactive Virtual Entities

# Advances in Neural Rendering and Mesh Generation

## PixelNeRF (2021)

## Instant Ngp (2022)

## Neuralangelo (2023)

## Magic3D (2023)

arXiv:2012.02190v3 [cs.CV] 30 May 2021

**pixelNeRF: Neural Radiance Fields from One or Few Images**

Alex Yu, Vickie Ye, Matthew Tancik, Angjoo Kanazawa  
UC Berkeley

Figure 1: **NeRF from one or few images.** We present pixelNeRF, a learning framework that predicts a Neural Radiance Field (NeRF) representation from a single (top) or few posed images (bottom). PixelNeRF can be trained on a set of multi-view images, allowing it to generate plausible novel view synthesis from very few input images without test-time optimization (bottom left). In contrast, NeRF has no generalization capabilities and performs poorly when only three input views are available (bottom right).

**Abstract**

We propose pixelNeRF, a learning framework that predicts a continuous neural scene representation conditioned on one or few input images. The existing approach for constructing neural radiance fields [27] involves optimizing the representation to every scene independently, requiring many calibrated views and significant compute time. We take a step towards resolving these shortcomings by introducing an architecture that conditions a NeRF on image inputs in a fully convolutional manner. This allows the network to be trained across multiple scenes to learn a scene prior, enabling it to perform novel view synthesis in a feed-forward manner from a sparse set of views (as few as one). Leveraging the volume rendering approach of NeRF, our model can be trained directly from images with no explicit 3D supervision. We conduct extensive experiments on ShapeNet benchmarks for single image novel view synthesis tasks with held-out objects as well as entire unseen categories. We further demonstrate the flexibility of pixelNeRF by demonstrating it on multi-object ShapeNet scenes and real scenes from the DTU dataset. In all cases, pixelNeRF outperforms current state-of-the-art baselines for novel view synthesis and single image 3D reconstruction. For the video and code, please visit the project website: <https://alexxyu.net/pixelnerf/>.

**1. Introduction**

We study the problem of synthesizing novel views of a scene from a sparse set of input views. This long-standing problem has recently seen progress due to advances in differentiable neural rendering [27, 20, 24, 40]. Across these approaches, a 3D scene is represented with a neural network, which can then be rendered into 2D views. Notably, the recent method neural radiance fields (NeRF) [27] has shown impressive performance on novel view synthesis of a specific scene by implicitly encoding volumetric density and color through a neural network. While NeRF can render photorealistic novel views, it is often impractical as it requires a large number of posed images and a lengthy per-scene optimization.

In this paper, we address these shortcomings by proposing pixelNeRF, a learning framework that enables predicting NeRFs from one or several images in a feed-forward manner. Unlike the original NeRF network, which does not make use of any image features, pixelNeRF takes spatial image features aligned to each pixel as an input. This image conditioning allows the framework to be trained on a set of multi-view images, where it can learn scene priors to perform view synthesis from one or few input views. In contrast, NeRF is unable to generalize and performs poorly when few input images are available, as shown in Fig. 1.

**Instant Neural Graphics Primitives with a Multiresolution Hash Encoding**

THOMAS MÜLLER, NVIDIA, Switzerland  
ALEX EVANS, NVIDIA, United Kingdom  
CHRISTOPH SCHIED, NVIDIA, USA  
ALEXANDER KELLER, NVIDIA, Germany

<https://nvlabs.github.io/instant-ngp>

Figure 1: We demonstrate instant training of neural graphics primitives on a single GPU for multiple tasks. In GigaPixel image we represent a gigapixel image by a neural network. SDF learns a signed distance function in 3D space whose zero level-set represents a 2D surface. Neural radiance caching (NRC) [Müller et al. 2021] employs a neural network that is trained in real-time to cache costly lighting calculations. Lastly, NeRF [Mildenhall et al. 2020] uses 2D images and their camera poses to reconstruct a volumetric radiance-and-density field that is visualized using ray marching. In all tasks, our encoding and its efficient implementation provide clear benefits: rapid training, high quality, and simplicity. Our encoding is task-agnostic; we use the same implementation and hyperparameters across all tasks and only vary the hash table size which trades off quality and performance. Tokyo gigapixel photograph © Trevor Dobson (CC BY-NC-ND 2.0), Lego bulldozer 3D model ©Harvard Datalab (CC BY-NC 2.0)

**Abstract**

Neural graphics primitives, parameterized by fully connected neural networks, can be costly to train and evaluate. We reduce this cost with a versatile new input encoding that permits the use of a smaller network without sacrificing quality, thus significantly reducing the number of floating point and memory access operations: a small neural network is augmented by a multiresolution hash table of trainable feature vectors whose values are optimized through stochastic gradient descent. The multiresolution structure allows the network to disambiguate hash collisions, making for a simple architecture that is trivial to parallelize on modern GPUs. We leverage this parallelism by implementing the whole system using fully-fused CUDA kernels with a focus on minimizing wasted bandwidth and compute operations. We achieve a combined speedup of several orders of magnitude, enabling training of high-quality neural graphics primitives in a matter of seconds, and rendering in tens of milliseconds at a resolution of 1920x1080.

**1. Introduction**

Additional Key Words and Phrases: Image Synthesis, Neural Networks, Encodings, Hashing, GPUs, Parallel Computation, Function Approximation.

**ACM Reference Format:**  
Thomas Müller, Alex Evans, Christoph Schied, and Alexander Keller. 2022. Instant Neural Graphics Primitives with a Multiresolution Hash Encoding. ACM Trans. Graph. 41, 4, Article 102 (July 2022), 15 pages. <https://doi.org/10.1145/3528223.3538127>

CCS Concepts: • **Computing methodologies** → Massively parallel algorithms; Vector / streaming algorithms; **Neural networks**

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ACM Trans. Graph., Vol. 41, No. 4, Article 102. Publication date: July 2022.

**Neuralangelo: High-Fidelity Neural Surface Reconstruction**

Zhaoshuo Li<sup>1,2</sup>, Thomas Müller<sup>1</sup>, Alex Evans<sup>1</sup>, Russell H. Taylor<sup>2</sup>, Mathias Unberath<sup>2</sup>, Ming-Yu Liu<sup>1</sup>, Chen-Hsuan Lin<sup>1</sup>  
<sup>1</sup>NVIDIA Research <sup>2</sup>Johns Hopkins University  
<https://research.nvidia.com/labs/dir/neuralangelo>

arXiv:2306.03092v2 [cs.CV] 12 Jun 2023

Figure 1: We present **Neuralangelo**, a framework for high-fidelity 3D surface reconstruction from RGB images using neural volume rendering, even without auxiliary data such as segmentation or depth. Shown in the figure is an extracted 3D mesh of a courthouse.

**Abstract**

Neural surface reconstruction has been shown to be powerful for recovering dense 3D surfaces via image-based neural rendering. However, current methods struggle to recover detailed structures of real-world scenes. To address the issue, we present **Neuralangelo**, which combines the representation power of multi-resolution 3D hash grids with neural surface rendering. Two key ingredients enable our approach: (1) numerical gradients for computing higher-order derivatives as a smoothing operation and (2) coarse-to-fine optimization on the hash grids controlling different levels of details. Even without auxiliary inputs such as depth, **Neuralangelo** can effectively recover dense 3D surface structures from multi-view images with fidelity significantly surpassing previous methods, enabling detailed large-scale scene reconstruction from RGB video captures.

**1. Introduction**

3D surface reconstruction aims to recover dense geometric scene structures from multiple images observed at different viewpoints [9]. The recovered surfaces provide structural information useful for many downstream applications, such as 3D asset generation for augmented/virtual/mixed reality or environment mapping for autonomous navigation of robotics. Photogrammetric surface reconstruction using a monocular RGB camera is of particular interest, as it equips users with the capability of casually creating digital twins of the real world using ubiquitous mobile devices.

Classically, multi-view stereo algorithms [6, 16, 33, 39] had been the method of choice for sparse 3D reconstruction. An inherent drawback of these algorithms, however, is their inability to handle ambiguous observations, e.g. regions with large areas of homogeneous colors, repetitive texture

**Magic3D: High-Resolution Text-to-3D Content Creation**

Chen-Hsuan Lin\*, Jun Gao\*, Luming Tang\*, Towaki Takikawa\*, Xiaohui Zeng\*, Xun Huang, Karsten Kreis, Sanja Fidler\*, Ming-Yu Liu\*, Tsung-Yi Lin  
NVIDIA Corporation  
<https://research.nvidia.com/labs/dir/magic3d>

**Abstract**

*DreamFusion* [33] has recently demonstrated the utility of a pre-trained text-to-image diffusion model to optimize Neural Radiance Fields (NeRF) [25], achieving remarkable text-to-3D synthesis results. However, the method has two inherent limitations: (a) extremely slow optimization of NeRF, leading to low-quality 3D models with a long processing time. In this paper, we address these limitations by utilizing a two-stage optimization framework. First, we obtain a coarse model using a low-resolution diffusion prior and accelerate with a sparse 3D hash grid structure. Using the coarse representation as the initialization, we further optimize a textured 3D mesh model with an efficient differentiable renderer interacting with a high-resolution latent diffusion model. Our method, dubbed *Magic3D*, can create high quality 3D mesh models in 40 minutes, which is 2x faster than *DreamFusion* (reportedly taking 1.5 hours on average), while also achieving higher resolution. User studies show 61.7% raters to prefer our approach over *DreamFusion*. Together with the image-conditioned generation capabilities, we provide users with new ways to control 3D synthesis, opening up new avenues to various creative applications.

**1. Introduction**

3D digital content has been in high demand for a variety of applications, including gaming, entertainment, architecture, and robotics simulation. It is slowly finding its way into virtually every possible domain: retail, online conferencing, virtual social presence, education, etc. However, creating professional 3D content is not for anyone — it requires immense artistic and aesthetic training with 3D modeling expertise. Developing these skill sets takes a significant amount of time and effort. Augmenting 3D content creation with natural language could considerably help democratize 3D content creation for novices and turbocharge expert artists.

Recently, *DreamFusion* [33] demonstrated its remarkable ability for text-conditioned 3D content generation by utilizing a pre-trained text-to-image diffusion model [38] that generates images as a strong image prior. The diffusion model acts as a critic to optimize the underlying 3D representation. The optimization process ensures that rendered images from a 3D model, represented by Neural Radiance Fields (NeRF) [25], match the distribution of photorealistic images across different viewpoints, given the input text prompt. Since the supervision signal in *DreamFusion* operates on very low-resolution images (64 × 64), *DreamFusion* cannot synthesize high-frequency 3D geometric and texture details. Due to the use of inefficient MLP architectures for the NeRF representation, practical high-resolution synthesis may not even be possible as the required memory footprint and the computation budget grows quickly with the resolution. Even at a resolution of 64 × 64, optimization times are in hours (1.5 hours per prompt on average using TPUv4).

In this paper, we present a method that can synthesize highly detailed 3D models from text prompts within a reduced computation time. Specifically, we propose a coarse-

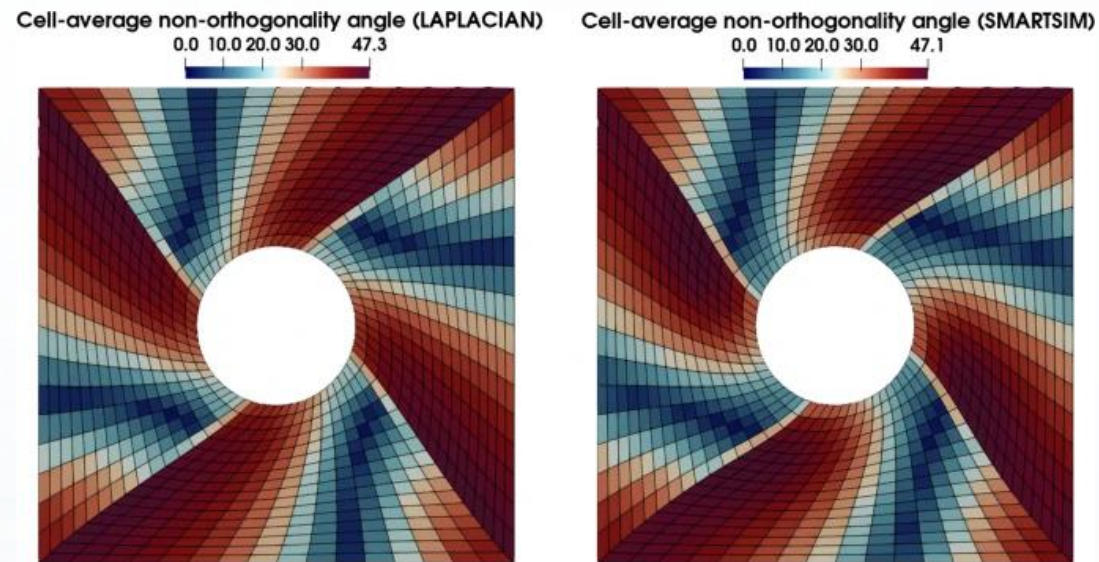
\*: equal contribution

Metric	PixelNeRF	Instant NGP	Neuralangelo
Rendering Time (ms)	10-30 per pixel	<1 per pixel	~100-500 per pixel
Scene Complexity	High	Medium-High	Very High
Photorealism	No/ Limited	Yes	Yes
Real-time Capability	No	Yes	No

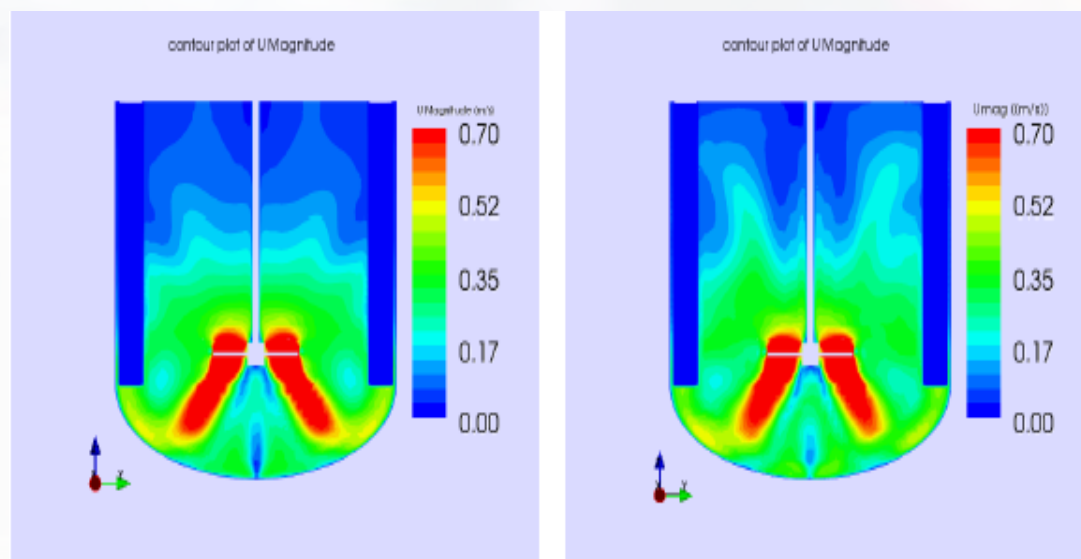
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A. Yu, V. Ye, M. Tancik and A. Kanazawa, "pixelNeRF: Neural Radiance Fields from One or Few Images," 2021 IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR), Nashville, TN, USA, 2021, pp. 4576-4585, doi: 10.1109/CVPR46437.2021.00455.  
 keywords: {Convolutional codes;Solid modeling;Computer vision;Three-dimensional displays;Image resolution;Computer architecture;Benchmark testing},  
 "Instant Neural Graphics Primitives with a Multiresolution Hash Encoding" Thomas Müller et al. ACM Transactions on Graphics (SIGGRAPH), July 2022a  
 Li, Zhaoshuo & Müller, Thomas & Evans, Alex & Taylor, Russell & Unberath, Mathias & Liu, Ming-Yu & Lin, Chen-Hsuan. (2023). Neuralangelo: High-Fidelity Neural Surface Reconstruction.  
 Lin, Chen-Hsuan & Gao, Jun & Tang, Luming & Takikawa, Towaki & Zeng, Xiaohui & Huang, Xun & Kreis, Karsten & Fidler, Sanja & Liu, Ming-Yu & Lin, Tsung-Yi. (2022). Magic3D: High-Resolution Text-to-3D Content Creation. 10.48550/arXiv.2210.04400

# Towards Real-Time Physically Accurate Simulations



Approximating mesh-motion Laplacian mesh motion solver in OpenFOAM with MLP

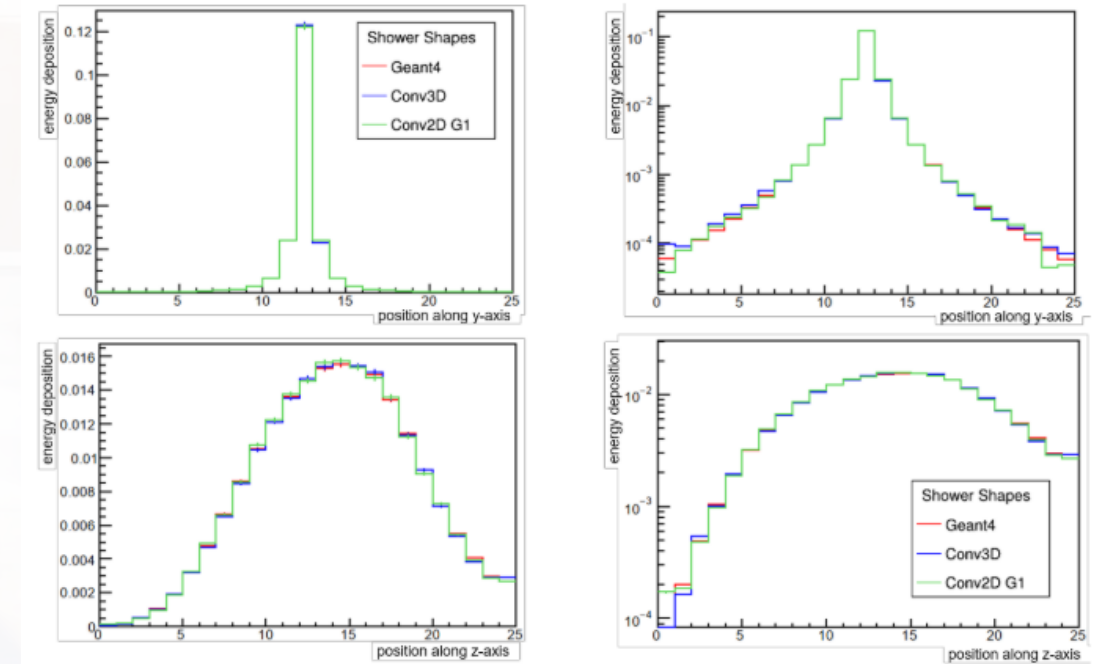


Using CNN to Solve Euler-Lagrange, Momentum Transfer, and Incompressible RANS Equations

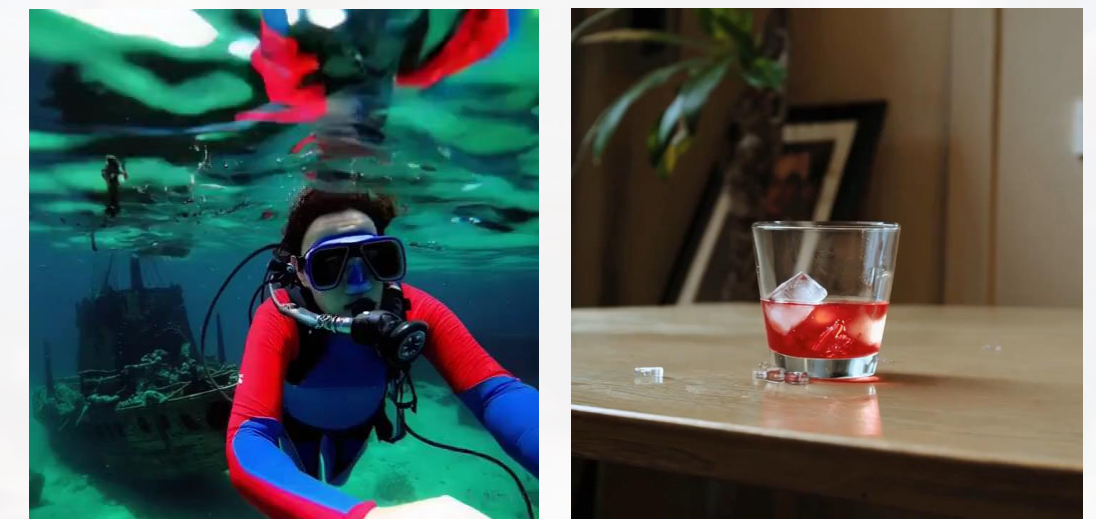
Gen AI

AI / ML

16



Simulating high energy physics calorimeter detector outputs with 2D GAN



Video generation models as general purpose simulators of the physical world?



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# Tensors Reshape Compute Architectures

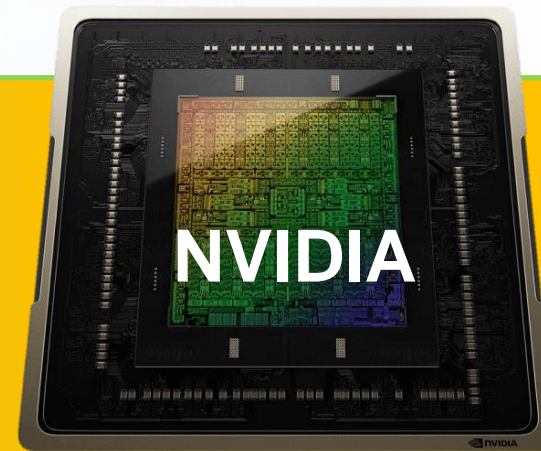
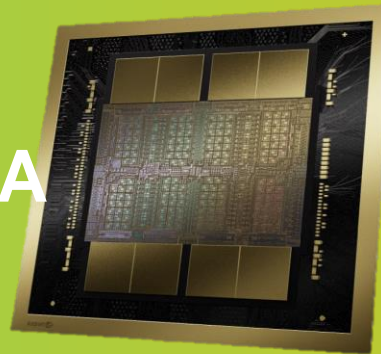
PC

Viz/P

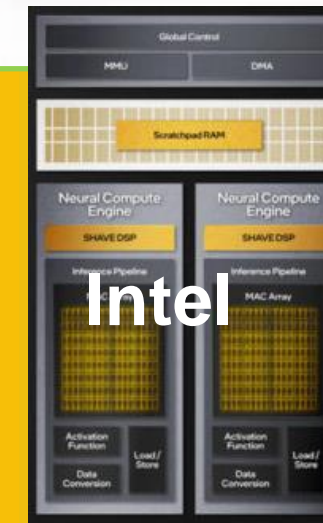
Edge/Client



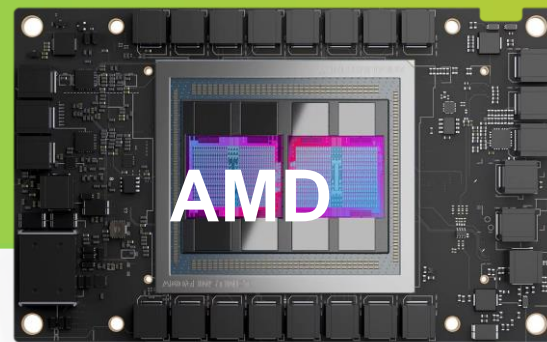
NVIDIA



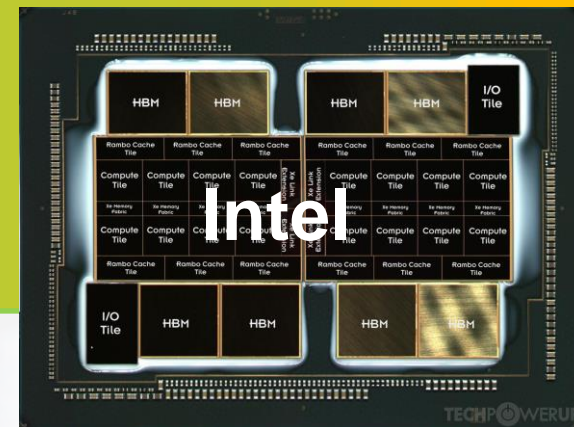
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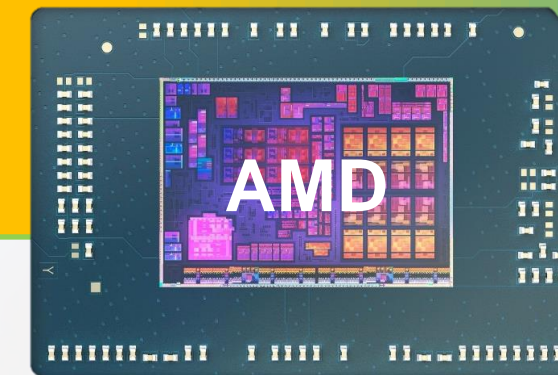
Intel



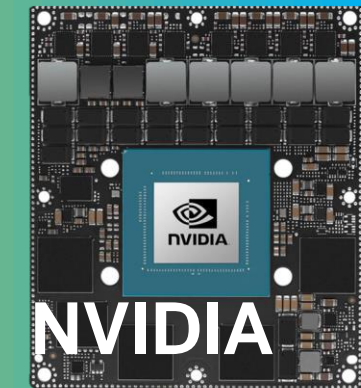
AMD



Intel



AMD



NVIDIA

# AI-optimized Portfolio from Model Development to Inferencing

## 80+ new and enhanced Infrastructure platforms – Pocket to Cloud, Edge to Core

### Data Management

#### Solutions

High Performance File System (w/WEKA)  
Object Storage Solutions (w/Cloudian)  
DSS-G / Spectrum Scale  
BeeGFS

**DM & DE** DE6600  
DM7100F DE6600  
DM5100  
DG7000



### ML & Data Analytics

**4-socket**  
SR850 V2  
SR850 V3 Intel  
SR860 V2  
SR860 V3 Intel

**2-Socket**  
SR650 V2  
SR650 V3 Intel  
SR655  
SR655 V3 AMD  
SR665  
SR665 V3 AMD



**ThinkSystem**

### Deep Learning Training HGX

ST650 V3 Intel  
SR670/75 V3 4-8x PCIe  
SR670/75 V3 4-GPU HGX

**NEW** SR680a V3 8-GPU HGX  
**NEW** SR685 V3 8-GPU HGX



SD650-I V3  
SD665-N V3

**NEW** SR780a 8-GPU HGX



### Data Science Workstation

**Edge** P1 Gen5  
**NEW** P3 Ultra P1 Gen6  
**NEW** P3 Tiny  
**Desktop**  
**NEW** PX  
**NEW** P7  
P620  
**NEW** P5  
**NEW** P3 Tower



### ThinkPad with Neural Processing Units

ThinkPad X13s Gen1 – 15 TOPS  
ThinkPad Z13 Gen2 – 11 TOPS  
ThinkPad Z16 Gen2 – 11 TOPS  
ThinkPad T14s AMD Gen4 – 11 TOPS  
ThinkPad T14 AMD Gen4 – 11 TOPS  
ThinkPad T16 AMD Gen2 – 11 TOPS  
ThinkPad X13 AMD Gen4 – 11 TOPS



Lenovo  
**ThinkPad**

### Edge AI

SE70 AWS  
Panorama

**Server**  
SE350  
**NEW** SE350 V2  
**NEW** SE360 V2  
SE450  
**NEW** SE455

**Clients**  
SE10, SE10-I  
M90  
SE30  
SE50  
SE70

AI Appliance

Lenovo  
**ThinkEdge**



### Appliances

**ThinkAgile MX Systems (Microsoft)**  
MX3330-F  
MX3330-H  
MX3331-F  
MX3331-H  
MX3530-F  
MX3530-H  
MX3531-F  
MX3531-H

**ThinkAgile HX Systems (Nutanix)**  
HX1330  
HX1331  
HX2330  
HX2331  
HX3330  
HX3331  
HX5530  
HX5531

**ThinkAgile VX Systems (VMware)**  
VX3331  
VX3530-G  
VX7531



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**ThinkStation**

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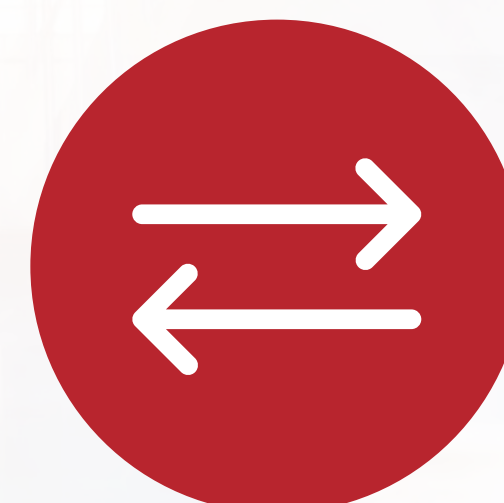
# Challenges ahead



Scalability  
& Energy Efficiency



Security &  
Privacy



Interoperability &  
Standards



Compute & Storage  
Optimization



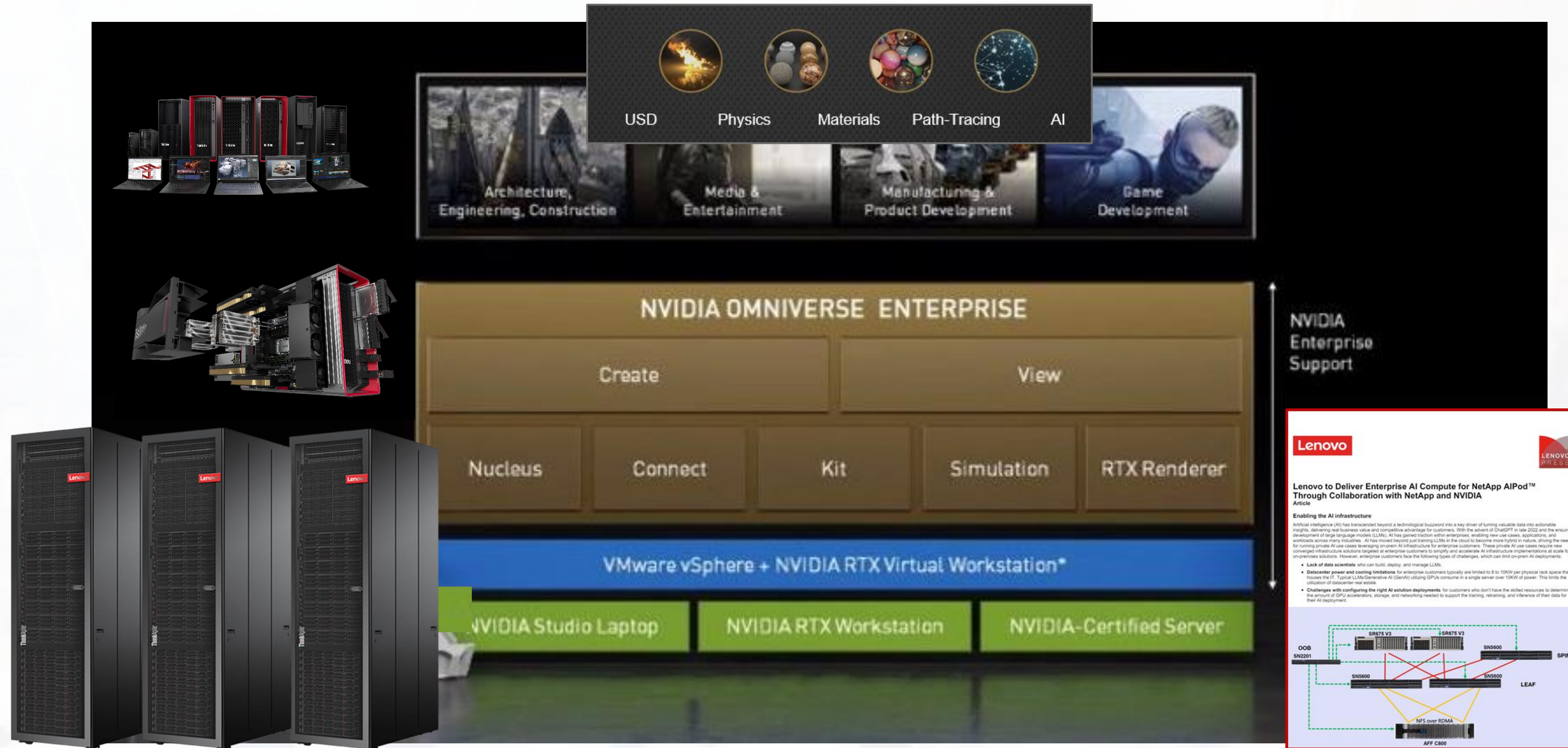
Ethic & Regulations

# Lenovo E2E – OVX Infrastructure Solutions

Through Collaboration with NetApp and NVIDIA



LENOVO - E2E – OVX INFRASTRUCTURE



**Lenovo** LENOVO PRESS

**Lenovo to Deliver Enterprise AI Compute for NetApp AI Pod™ Through Collaboration with NetApp and NVIDIA**  
Article

**Enabling the AI infrastructure**

Artificial intelligence (AI) has transcended beyond a technological buzzword into a key driver of turning valuable data into actionable insights, delivering real business value and competitive advantage for customers. With the advent of ChatGPT in late 2022 and the ensuing development of large language models (LLMs), AI has gained traction within enterprises, enabling new use cases, applications, and workloads across many industries. AI has moved beyond just training LLMs in the cloud to become more hybrid in nature, driving the need for running private AI use cases leveraging on-prem AI infrastructure for enterprise customers. These private AI use cases require new converged infrastructure solutions targeted at enterprise customers to simplify and accelerate AI infrastructure implementations at scale for on-premises solutions. However, enterprise customers face the following types of challenges, which can limit on-prem AI deployments:

- **Lack of data scientists** who can build, deploy, and manage LLMs.
- **Datacenter power and cooling limitations**, for enterprise customers typically are limited to 8 to 10KW per physical rack space that houses the IT. Typical LLMs/Generative AI (GenAI) utilizing GPUs consume in a single server over 10KW of power. This limits the utilization of datacenter real estate.
- **Challenges with configuring the right AI solution deployments** for customers who don't have the skilled resources to determine the amount of GPU accelerators, storage, and networking needed to support the training, retraining, and inference of their data for their AI deployment.



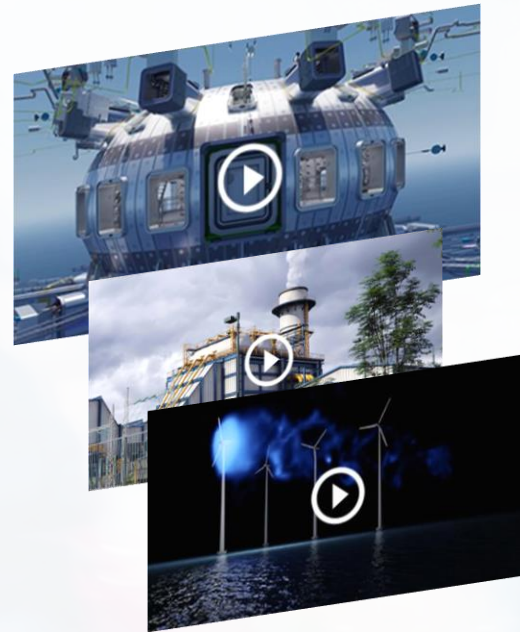
# The benefits of MV tech application embrace all industries.

## Automotive



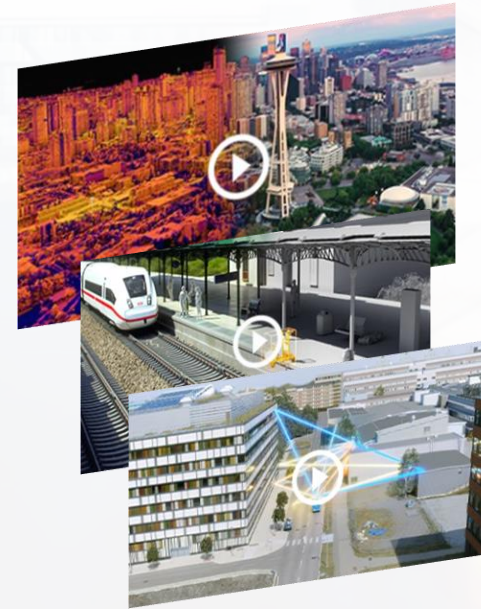
- Fast-Track Industrial Factory Planning
- Developing Custom Applications for Factory Planners

## Energy



- Accelerating Fusion Reactor Design and Development <sup>21</sup>
- Reducing Downtime and Unplanned Maintenance
- Optimizing Wind Farm Design and Electricity Generation

## Infrastructure



- Transforming Telco Network Planning and Operations
- Simulating and Optimizing Autonomous Railway Networks
- Testing and Optimizing 5G Deployment

## Retail



- Autonomous Warehouse Robots
- Retail Layout
- Optimizing Distribution Center Throughput

## Science



- Accelerating Carbon Capture and Storage
- Visualizing High-Resolution, Global-Scale Climate Data
- Accelerating Climate Research
- Visualizing Molecular Dynamics
- Brain Digital Twin

# Industrial Metaverse

# Are we there yet?

## Takeaways:

### Evolving DT Concept

The extended and enhanced use of digital twins is at the core of the Industrial Metaverse. AI applications can speed up 3D asset creation and prototyping while providing more intelligent capabilities to DT

### AI-Powered Metaverse

Integrating AI into the HPC framework for the Industrial Metaverse unlocks new capabilities, driving innovation and efficiency in high-fidelity rendering and physical simulations.

### Metaverse-Ready Infrastructure

The key technologies for achieving extended whole-system digital twins are not yet mature, but advances in AI, edge computing, and cloud infrastructure are rapidly closing the gap.

### Challenges

Key issues include security, scalability, latency, costs, skill gaps, and regulatory compliance (including AI and data governance)

### Future Trends

Accelerators mem bw will keep increasing, AI eats HPC, Raytracing engine will be integrated into AI superchips (i.e.: NVIDIA DGX) or Viz card will start employing DGX-like architectures



# Forum **TERATEC 24**

# thanks.

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